








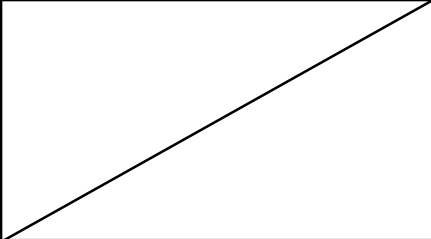





# ***HX & CODESYS Training***



## Lineup

Programming software		Compact type	Modular type
Ladder Editor (since 1997) 	LD	MICRO-EH 	EH-150 
Control Editor (since 2006) 	LD	MICRO-EHV 	EH-150 EHV series 
HX-CODESYS (since 2016) 	LD, FBD, IL, ST, SFC, CFC (IEC61131-3)	MICRO-EHV+ 	EH-150 EHV+ series 
(old version: EHV-CODESYS)			HX series 

Expansion units are compatible. 

I/O modules are compatible. 

## Outline of IEC61131-3

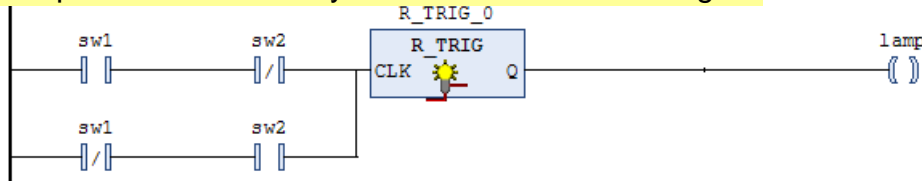
## Features

- Standardized PLC programming way
- Programming with the use of variable name
- 5 programming languages
- Structured program
- High re-usability of program / function

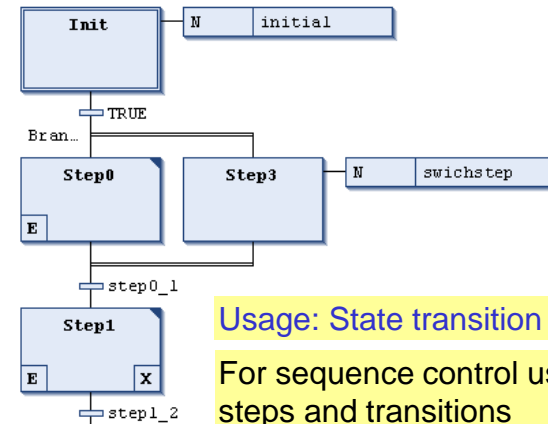
## IEC 4 languages + 1 element + non-IEC 1 language

LD (Ladder Logic) Usage: Interlock circuit etc.

Graphic editor for binary variables and interlocking



SFC (Sequential Function Chart)

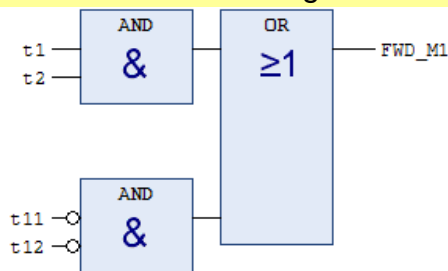


Usage: State transition processing etc.

For sequence control using steps and transitions

FBD (Function Block Diagram) Usage: Data flow etc.

Graphic editor for networking and data flow



ST (Structured Text)

```

1 count_M3 := count_M3 + 1;
2 L2_wait_timer (IN:= FALSE, PT:= T#3.6S);
3 L2_wait_timer (IN:= TRUE);
4 FOR i := 0 TO count_T
5     L2_wait_timer();
6 END_FOR;
7 elp_wait:= L2_wait_timer.ET;
8 IF count_GS < 24 THEN
9     WHILE test_out5 < 10 DO
10        max_R2:=max_R2+1;
11    END_WHILE
12 END_IF;
    
```

Usage: Conditional branching, repeating etc.

For conditional branching and loop

IL (Instruction List)

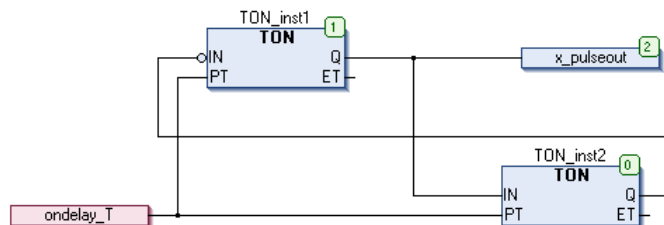
```

1  CAL          TON_IL (
   IN:= ton_input,
   PT:= T#50000S,
   ET=> ton_elp)
2  LD          TON_IL.Q
   ST          ton_output
3  LD          Lift_A
   OR          sta_L4_covyr
   ST          IL_sample_out
    
```

Usage: Miniaturization of applications etc.

For small application or restoring old programs

CFC (Continuous Function Chart)



Usage: emphasis on visibility, small applications, etc.

FBD editor with free layout incl. feedback paths

## IEC data types (Elementary data types)

No.	Group	Data type	Size	Range
1	Boolean	BOOL	1	0, 1 (TRUE, FALSE)
2	Bit array	BYTE	8	0 ~ 255
3		WORD	16	0 ~ 65,535
4		DWORD	32	0 ~ 4,294,967,295
5		LWORD	64	0 ~ $2^{64} - 1$
6	Integer	SINT	8	-128 ~ 127
7		INT	16	-32,768 ~ 32,767
8		DINT	32	-2,147,483,648 ~ 2,147,483,647
9		LINT	64	$-2^{63} \sim 2^{63} - 1$
10	Unsigned integer	USINT	8	0 ~ 255
11		UINT	16	0 ~ 65,535
12		UDINT	32	0 ~ 4,294,967,295
13		ULINT	64	0 ~ $2^{64} - 1$
14	Real number	REAL	32	$\pm 1.175... \times 10^{-38} \sim 3.402... \times 10^{38}$
15		LREAL	64	$\pm 2.225... \times 10^{-308} \sim 1.797... \times 10^{308}$
16	Time	TIME	32	0 ~ 4,294,967,295 ms
17		LTIME	64	$2^{64} - 1$ ms

## IEC data types (Elementary data types)

No.	Group	Data type	Size	Format
18	1-byte string	STRING	8x n	'abc'
19	2-byte string	WSTRING	16x n	"abc"
20	Date	DATE	32	d#2016-12-31 or DATE#2016-12-31
21	Date and Time	DATE_AND_TIME	32	dt#2016-12-31-23:59:59 or DATE_AND_TIME#2016-12-31-23:59:59
22	Time	TIME_OF_DAY	32	tod#23:59:59 or TIME_OF_DAY#23:59:59

## IEC data types (User-defined types)

No.	Group	Format
1	Array	ARRAY [0..255] OF WORD; ARRAY [0..11, 0..22, 0..33] OF REAL; // 3-dimentional array
2	Partial range data type	WORD(0..4095)
3	Enumerator	TYPE COLOR: (Red, Yellow, Green); END_TYPE
4	Structure	TYPE STRUCT_sample STRUCT ID : WORD; Flag : BOOL; Weight : REAL; END_STRUCT END_TYPE

## Numeric literals

No.	Group	Example	Remarks
1	Integer	-12, 0, +123	Decimal number
2	Real number	0.0, 3.14159, 1.234_567	Underline is ignored
3	Exponent	1.2E6, 1.23E+3, 1.23E-6	
4	Binary	2#11, 2#1110_1111	Underline is ignored
5	Hexadecimal	16#FF, 16#1234_FFFF	Underline is ignored
6	BOOL	FALSE, TRUE	

## Time and Date literals

No.	Group	Example	Remarks
1	Time	TIME#30ms, TIME#25h15m or T#30ms, T#25h15m	d: Day h: Hour m: Minute s: Second ms: Milli second us: Micro second
2	Date	DATE#2016-1-1, DATE#1999-12-31 Or D#2016-1-1, D#1999-12-31	
3	Time of day	TIME_OF_DAY#15:29:59, TIME_OF_DAY#15:30 Or TOD#15:29:59, TOD#15:30	
4	Date and time	DATE_AND_TIME#2016-12-31-23:59:59 Or DT#2016-12-31-23:59:59	

## IEC identifier (Variable)

Allowed characters : a to z, A to Z, 0 to 9 and \_ (underscore)

### Remarks

- Beginning with a number is not allowed.
- Multiple leading or multiple embedded underlines are not allowed.
- Upper and lower case letters are identical. ("abc" and "ABC" are identical)
- Reserved words (FOR, WORD, AND, etc.) are not allowed.

## IEC Instructions (FUNCTION)

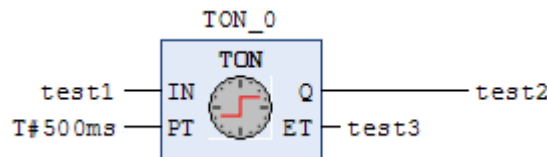
Group	Name	Description	Group	Name	Description
Numeric operations	ABS	Absolute value	Selections	SEL	Input multiplexer
	SQRT	Square root		MAX	Maximum value
	LN	Natural logarithm		MIN	Minimum value
	LOG	Logarithm		LIMIT	Limiter
	EXP	Exponential function		MUX	Expandable multiplexer
	SIN	Sine	Comparisons	GT	Greater than
	COS	Cosine		GE	Greater or Equal
	TAN	Tangent		EQ	Equal
	ASIN	Arc sine		LE	Less or Equal
	ACOS	Arc cosine		LT	Less than
ATAN	Arc tangent	NE	Not Equal		
Arithmetic operations	ADD	Addition	Strings	LEN	Length
	MUL	Multiplication		LEFT	Extraction of left edge letter
	SUB	Subtraction		RIGHT	Extraction of right edge letter
	DIV	Division		MID	Extraction of middle letter
	MOD	Surplus		CONCAT	Concatenate
	EXPT	Power		INSERT	Insert
	MOVE	Assignment		DELETE	Delete
Logical operations	AND	Logical conjunction		REPLACE	Replace
	OR	Logical disjunction		FIND	Find
	XOR	Exclusive OR			
	NOT	Negation			

Refer Help for details ([CODESYS Development System > Reference, Programming > Operators](#))

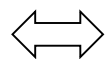
## IEC Instructions (FUNCTION BLOCK)

Group	Name	Description
Numeric operations	SR	Bistable function block (set dominant)
	RS	Bistable function block (reset dominant)
Edge detection	R_TRIG	Rising edge
	F_TRIG	Falling edge
Counter	CTU	Up counter
	CTD	Down counter
	CTUD	Up-down counter
Timer	TP	Pulse
	TON	On-Delay Timer
	TOF	Off-Delay Timer

Example) TON at LD/FBD and ST



Equivalent











```
TON_0 (IN:=test1, PT:=T#500MS, Q=>test2, ET=>test3);
```

## IEC Instructions (Dedicated in ST)

Group	Name
Addition	+
Subtraction	-
Multiplication	*
Division	/
Surplus	MOD
Comparisons	<, >, <=, >=
Equality	=
Inequality	<>
Logical conjunction	AND
Logical disjunction	OR
Exclusive OR	XOR
Brackets	()
Pointer reference	^
Negation	NOT
Power	EXPT

Group	Name	Description
Assignment	:=	Right to left
Function call	<Function name>()	Function or function block call
Return	RETURN	Exit from function, function block or program
Branch	IF - THEN ... ELSIF - THEN ... ELSE ... END_IF	A group of statements is to be executed only if the associated Boolean expression evaluates to TRUE.
	CASE ... OF ... ELSE ... END_CASE	Multidirectional branching in accordance with value of a variable
Iteration	FOR ... TO ... BY ... DO ... END_FOR	Iteration the number of prepared times
	WHILE - DO ... END_WHILE	Iteration until the condition gets FALSE
	REPEAT ... UNTIL ... END_REPEAT	Iteration until the condition gets TRUE
	CONTINUE	Skip remain part of one loop
	EXIT	Exit iteration loop

## IEC Instructions (Dedicated in LD)

Group	Name	Description
Static contact		Contact
		Negated contact
Edge detection contact		Rising edge detection contact
		Falling edge detection contact
General coil		Coil
		Negated coil
Latch coil		Set coil
		Reset coil

## What's POU?

**POU**: Program Organization Unit ≡ Program sheet  
⇒ The minimum unit of program. There are 3 types of POU.

- Program (PRG)
- Function Block (FB)
- Function (FUN)

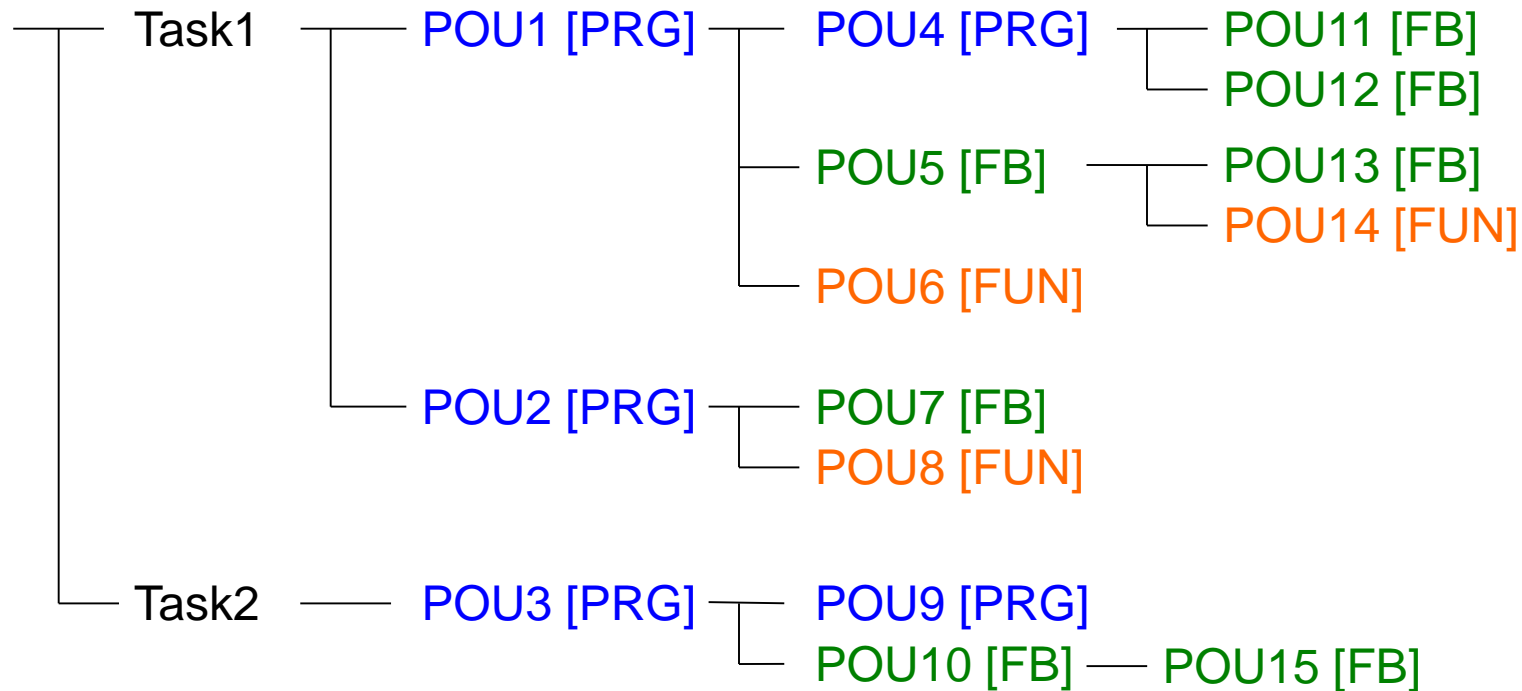
Type	Called by Task	How to call	I/O limitation	Store data
PRG	✓	Direct call	Free	✓
FB	-	Instance call	Free	✓
FUN	-	Direct call	Only 1 Output	-

**[Note]** Note: Do not mix up FB and FBD. FB is one of the type of POU.  
FBD is a name of programming language.

## What's Task?

**Task:** Handles priority and execution cycle of POU.

## Software model of Task and POU



\* POU = Program Organization Unit

## Global variables / Local variables

- Global variables: can be used commonly in all POU in a project
- Local variables: are valid in a POU where the variable is defined.

### Example

#### Global variable

Name: Test, Data type: WORD

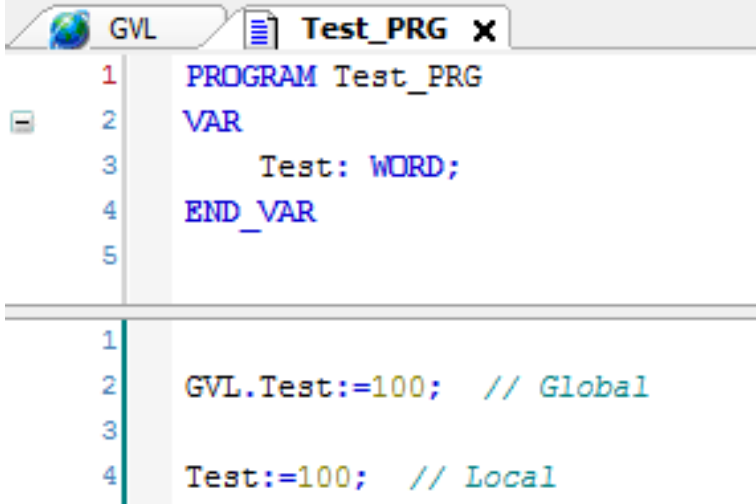
```
1 {attribute 'qualified_only'}
2 VAR_GLOBAL
3     Test: WORD;
4 END_VAR
5
```

#### Local variable

Name: Test, Data type: WORD

```
1 PROGRAM Test_PRG
2 VAR
3     Test: WORD;
4 END_VAR
```

### Usage example in POU "Test\_PRG"



The screenshot shows a code editor with two tabs: 'GVL' and 'Test\_PRG x'. The 'Test\_PRG' tab is active and displays the following code:

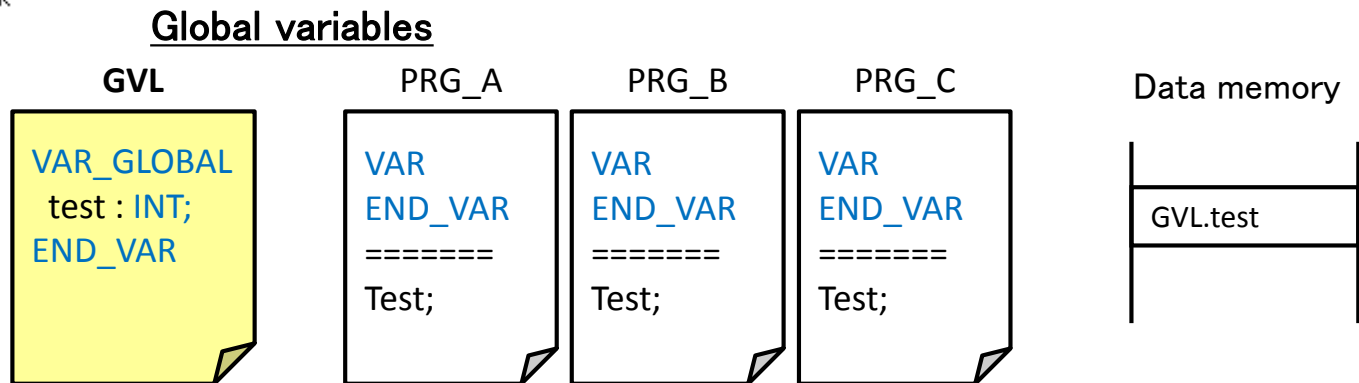
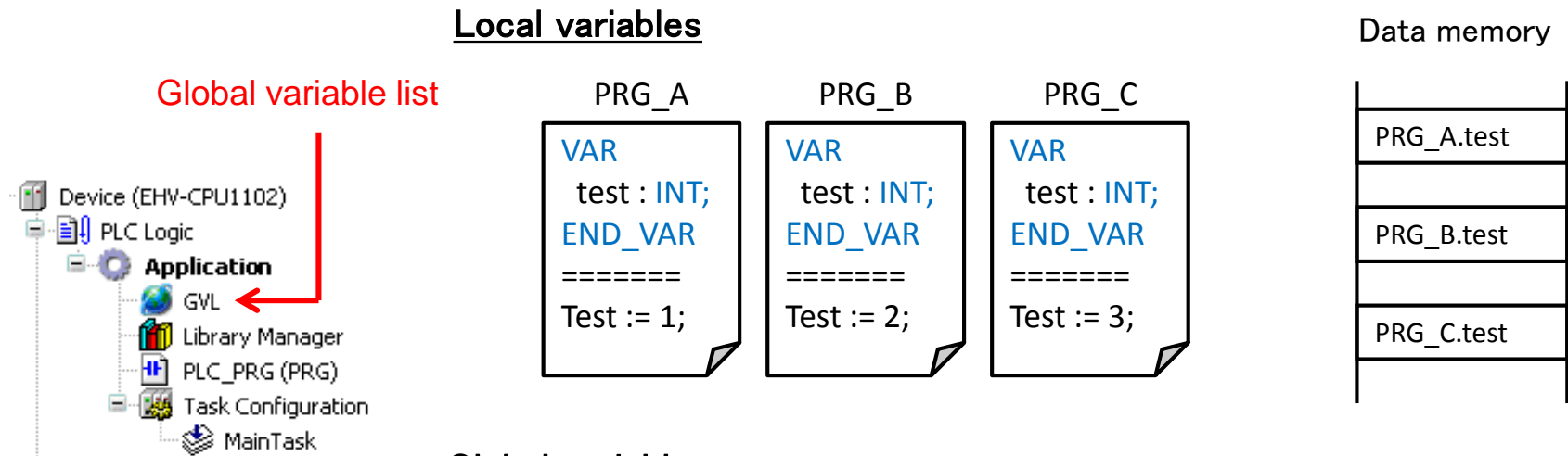
```
1 PROGRAM Test_PRG
2 VAR
3     Test: WORD;
4 END_VAR
```

---

```
1
2 GVL.Test:=100; // Global
3
4 Test:=100; // Local
```

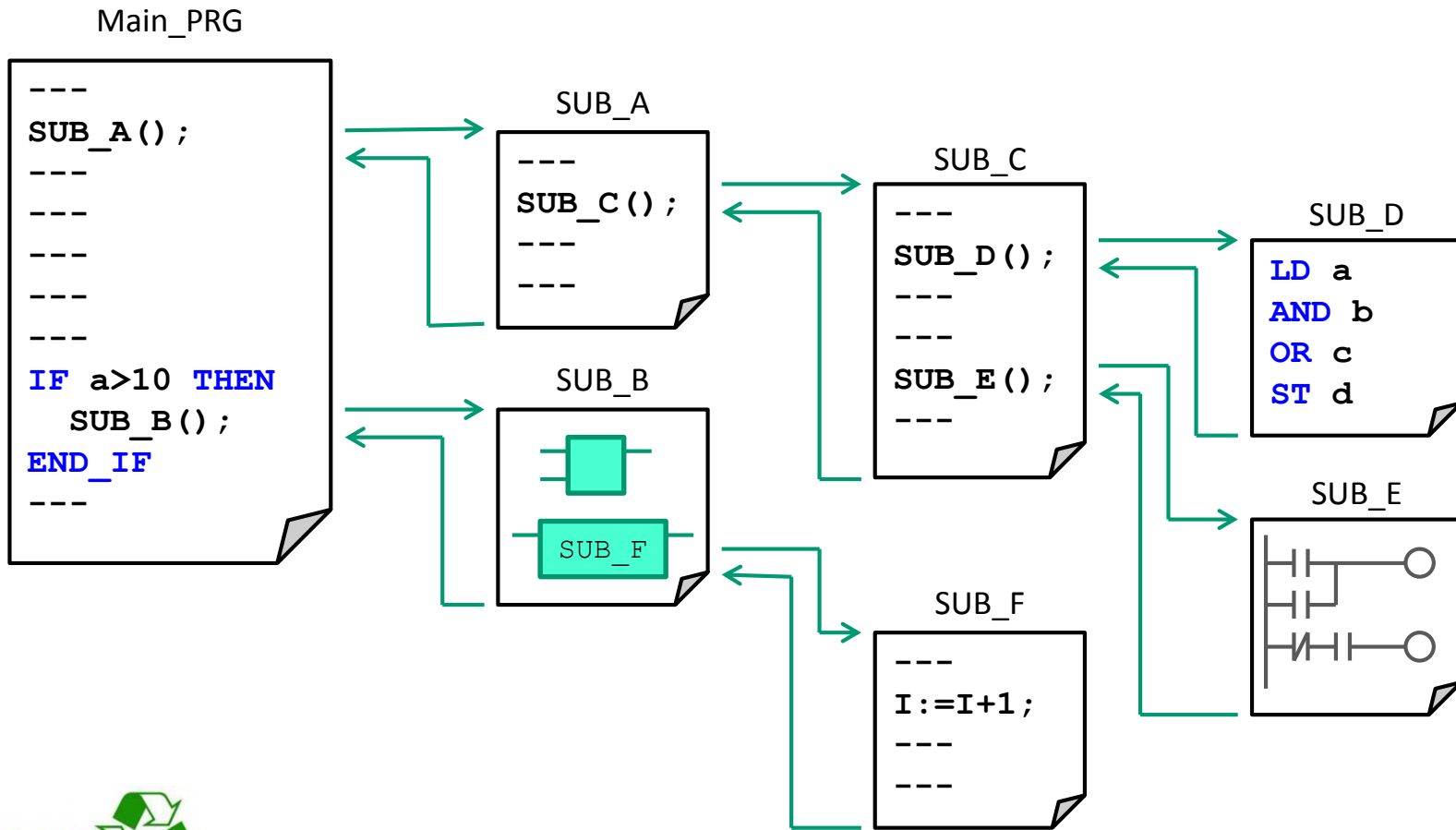
## Advantage of IEC61131-3 programming

## Global variables / Local variables



- Effective programming among multiple developers
- High program reusability

## Structured Program



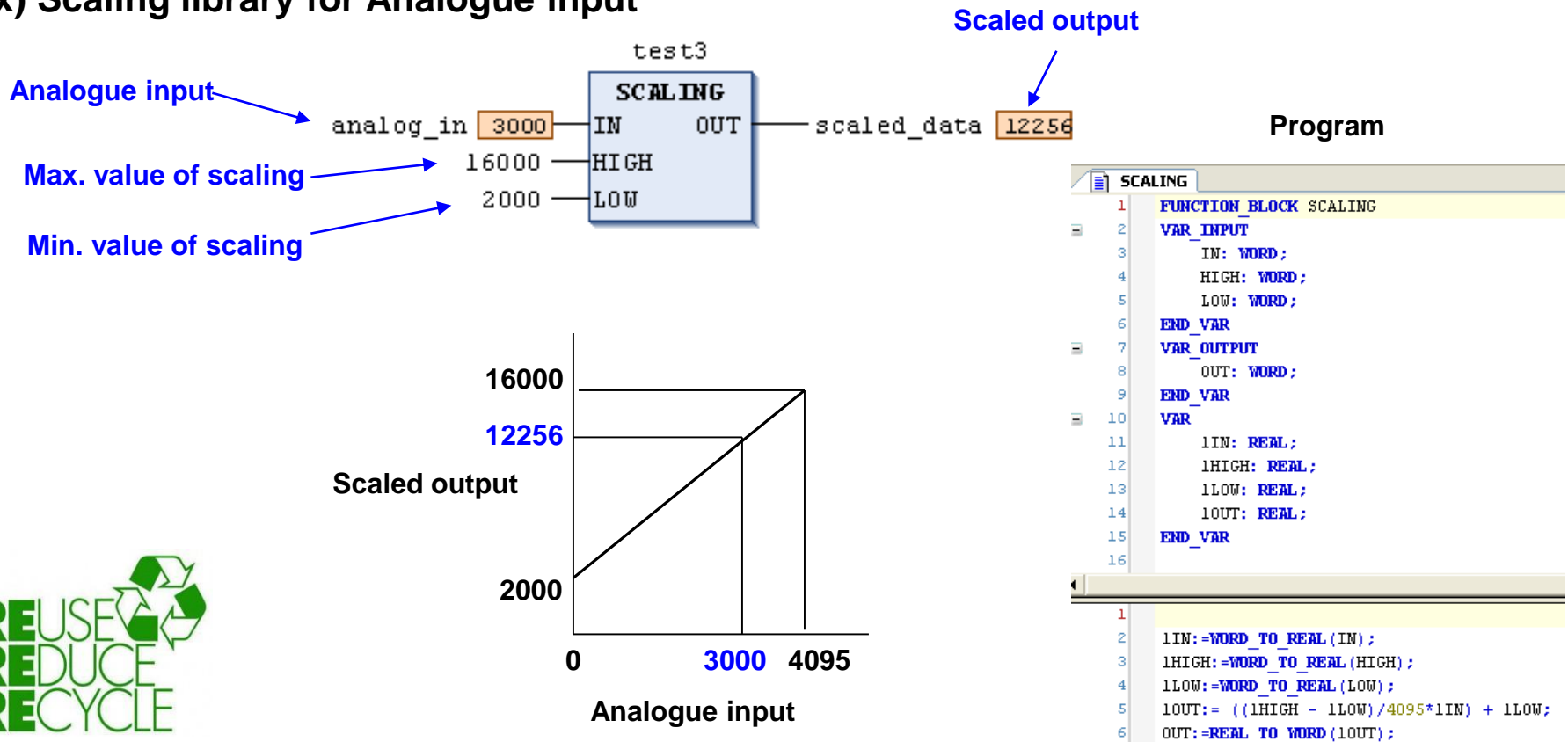
- Effective programming among multiple developers
- High program reusability



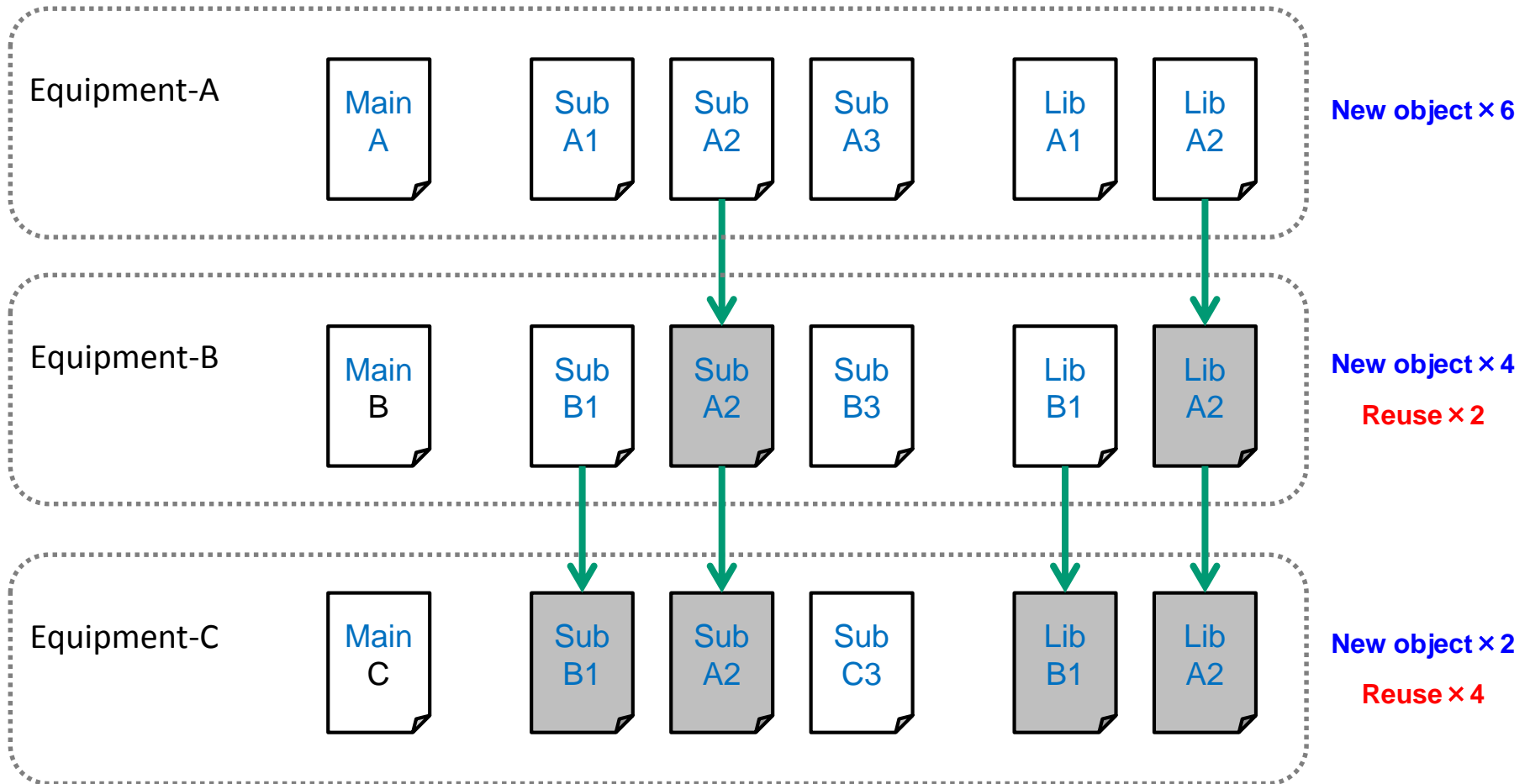
## Library

If you make frequently used functions as library, you can easily call them from other programs. → **Program reusability**

### Ex) Scaling library for Analogue input



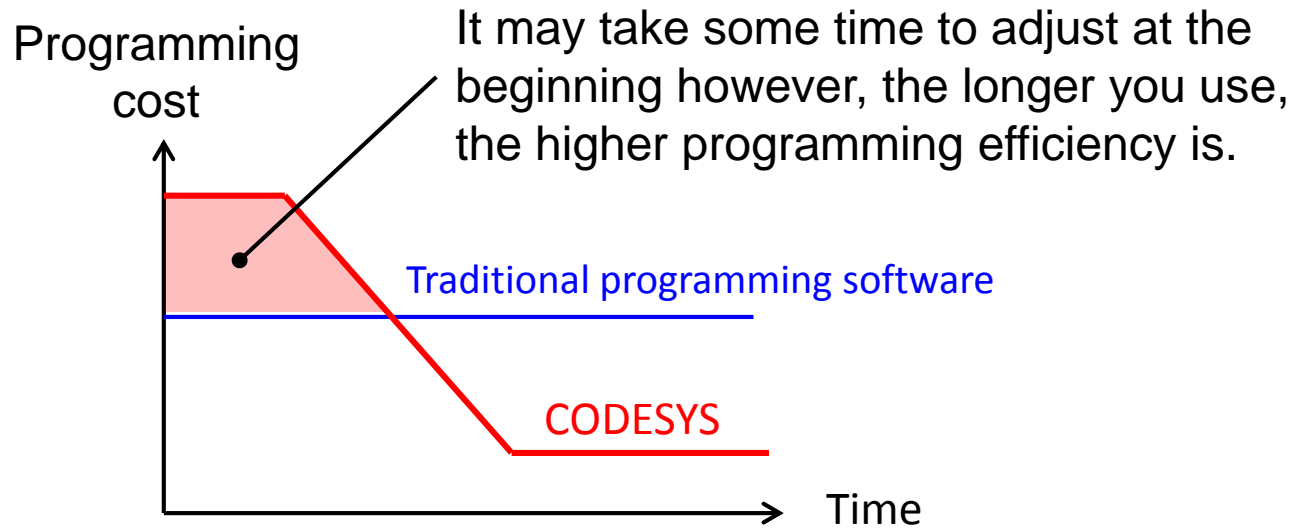
# Advantage of IEC61131-3 programming



Features like Global variables, Structured programming, Library make Programming / debugging efficiency increased as you make programs.

## High efficiency programming

→ Cost reduction for customers



# Features of CODESYS

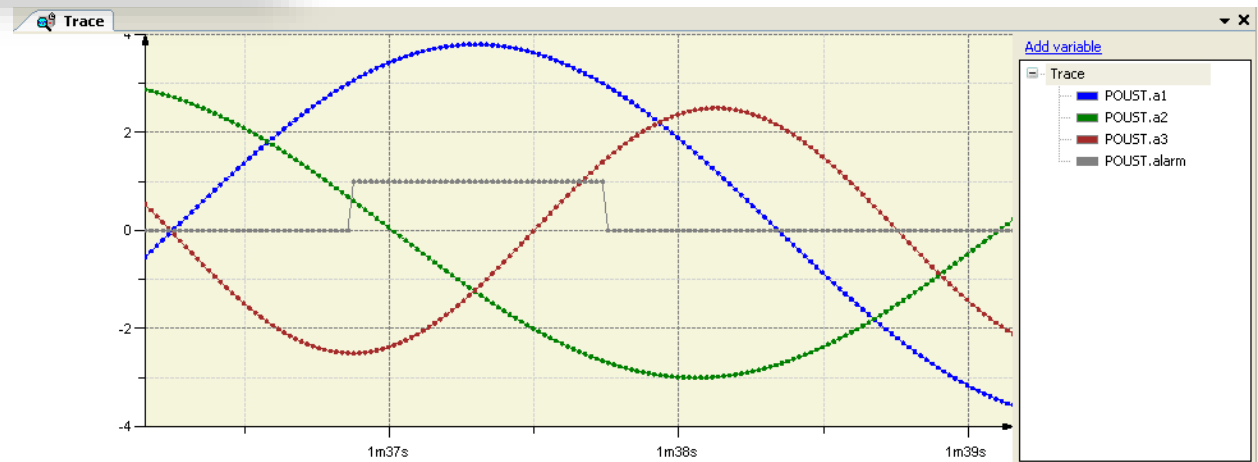
## Visualization (Simple SCADA) and Trace



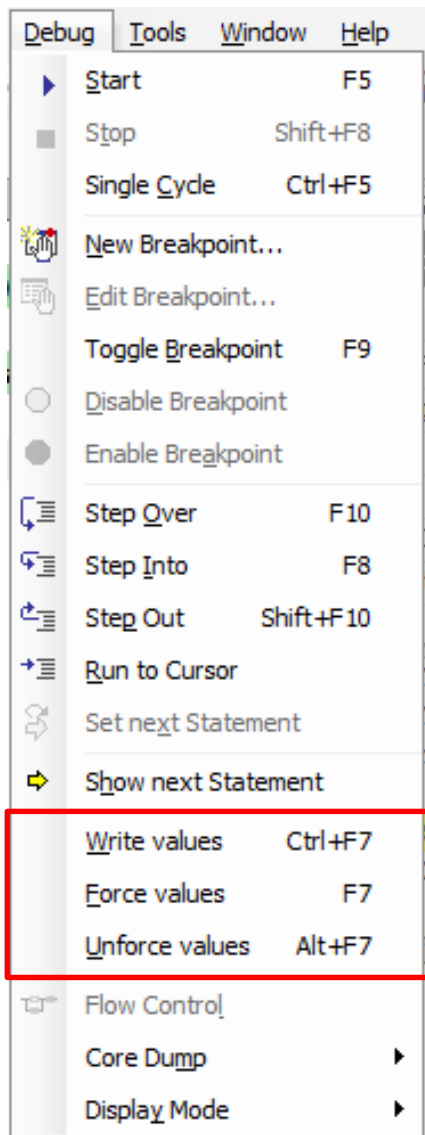
Visualization: Displayed on CODESYS

Web Visualization: Displayed on web browser

## Trace

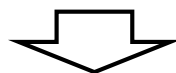


## Write value / Force value



Write value (Set a prepared value to a variable)

```
test 0 := var1 0 <3> * 2;
```



[Ctrl] + [F7]

```
test 6 := var1 3 * 2;
```

Force value (Fix value of a variable regardless of program)

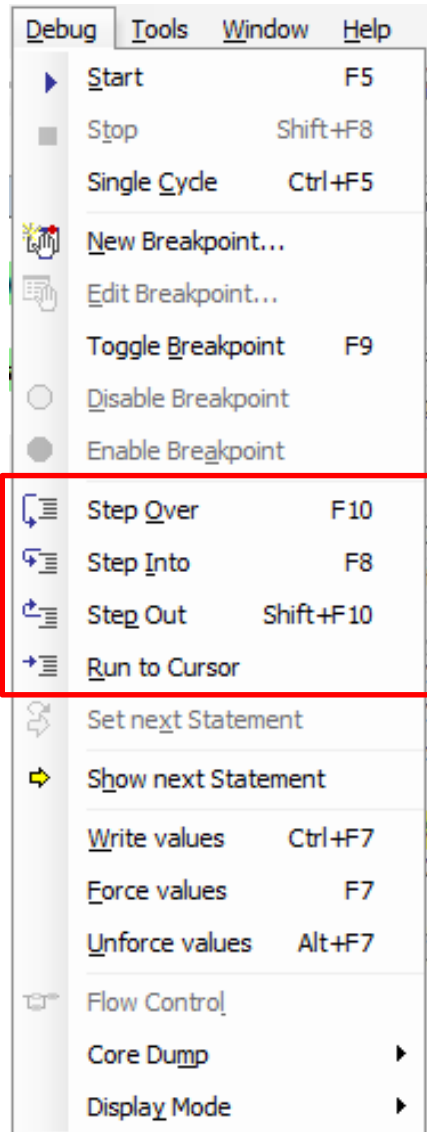
```
test 6 <100> := var1 3 * 2;
```



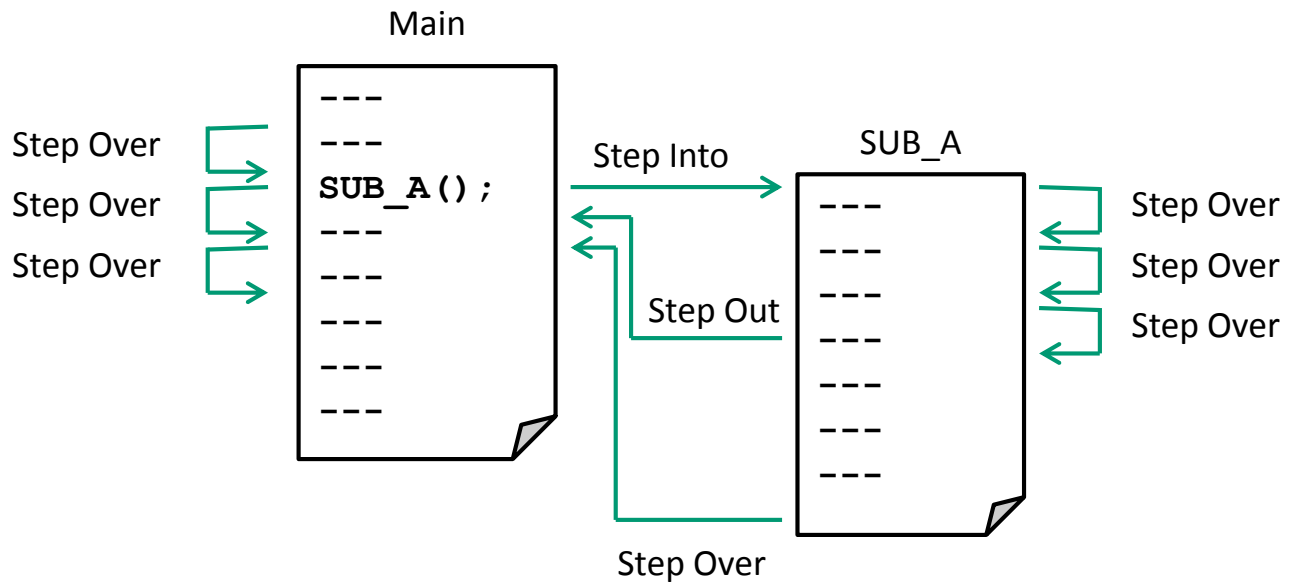
[F7]

```
test F 100 := var1 3 * 2;
```

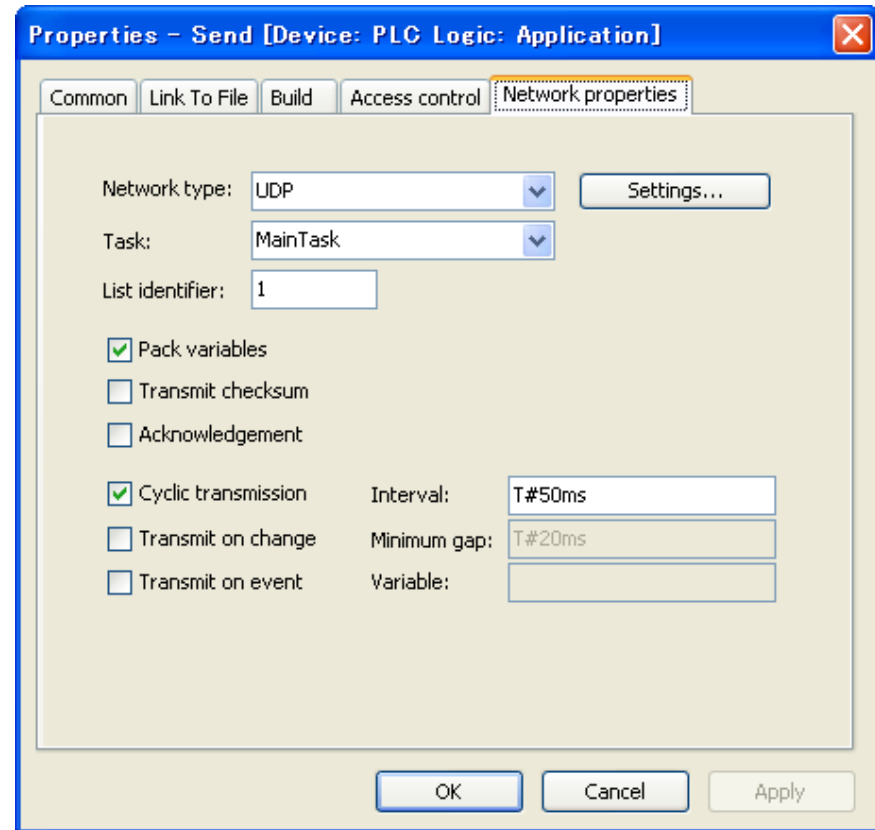
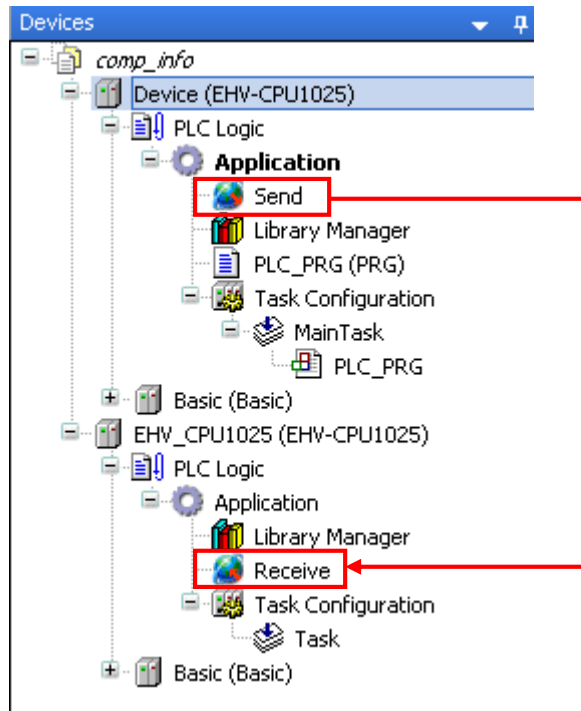
## Single scan, Break point, step execution



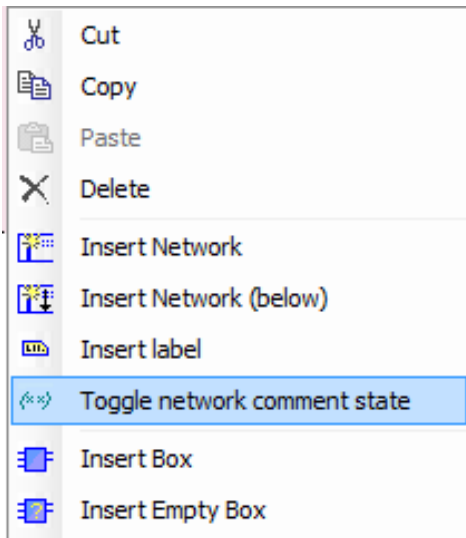
```
11 IF test1 0 >6 THEN  
12 S2 ();  
13 test1 0 :=0;  
14 END_IF;  
15  
16 test3 1266 :=test3 1266 +1;  
17
```



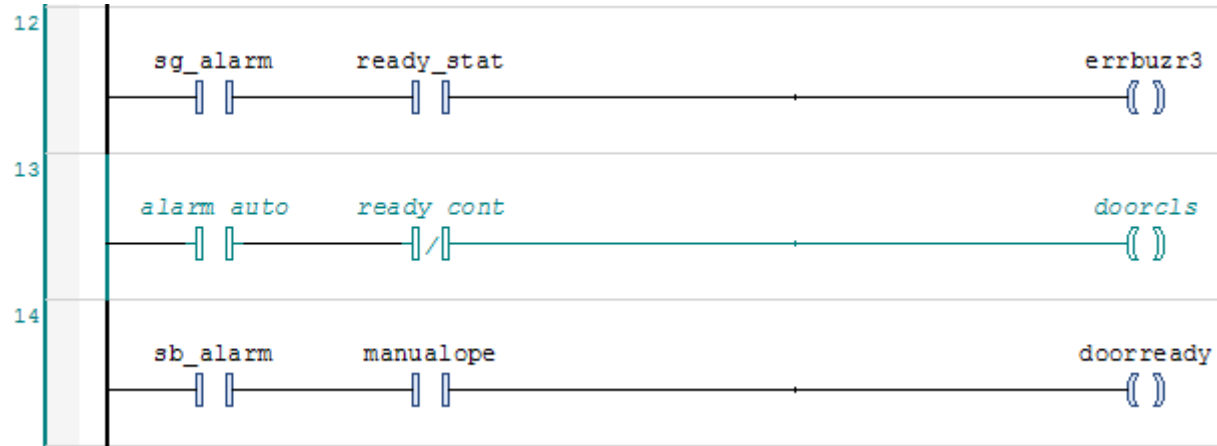
## Global network variable: Automatic UDP communication



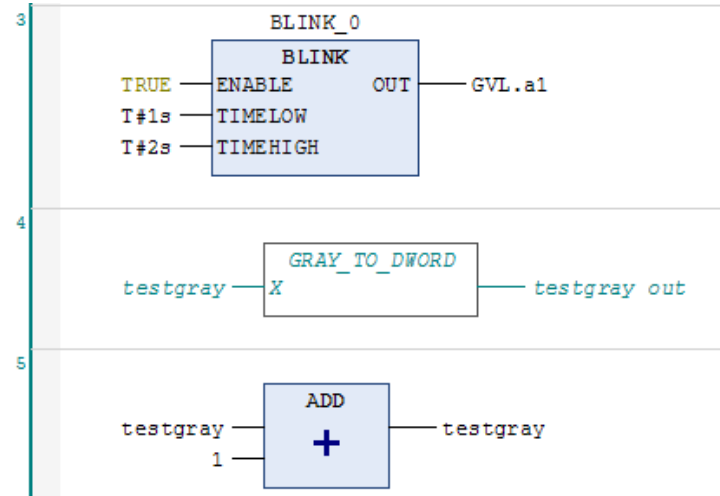
## Comment out (Deactivation of instructions)



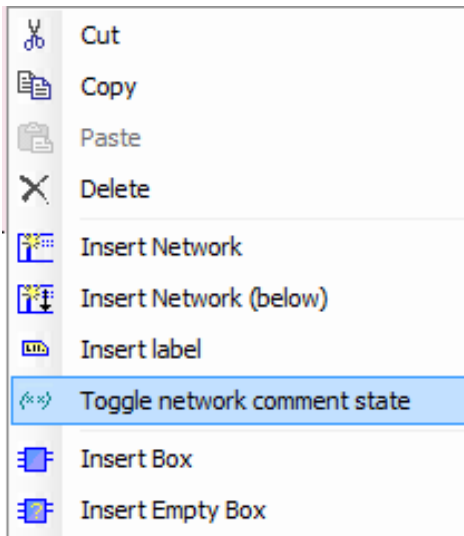
LD



FBD



## Comment out (Deactivation of instructions)



ST

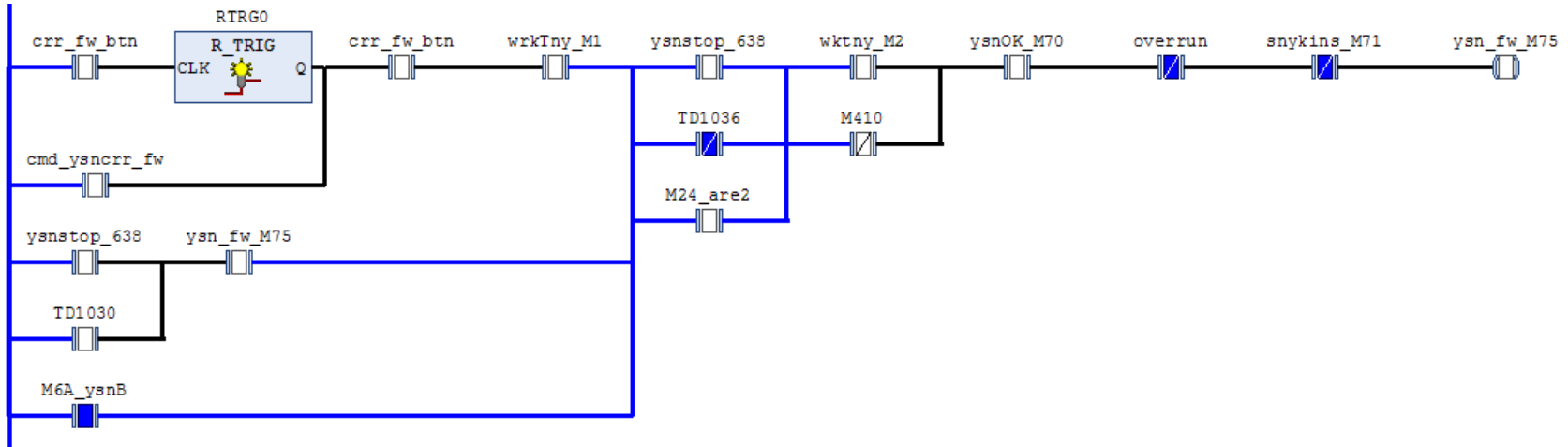
Single line: //

```
12 // ***** TRACE data *****
13 trace_data1:=SIN(k1);
14 trace_data2:=1.5*SIN(k1*3+1);
15 //trace_data3:=2*SIN(k1+2);
16 k1:=k1+0.01;
17 trace_x1:=trace_x1+1;
18 trace_data4:=trace_x1.6;
19
```

Multiple lines: (\* \*)

```
12 // ***** TRACE data *****
13 trace_data1:=SIN(k1);
14 trace_data2:=1.5*SIN(k1*3+1);
15 trace_data3:=2*SIN(k1+2);
16 (*
17 k1:=k1+0.01;
18 trace_x1:=trace_x1+1;
19 trace_data4:=trace_x1.6;
20 *)
```

Monitor of Ladder: Displayed at blue line for conducted circuit



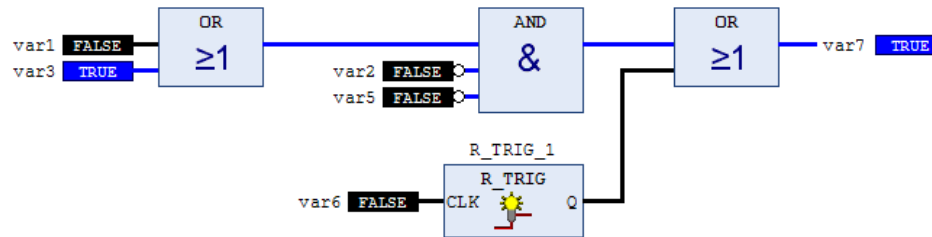
Flow control: Currently executed instructions are displayed in green.

```

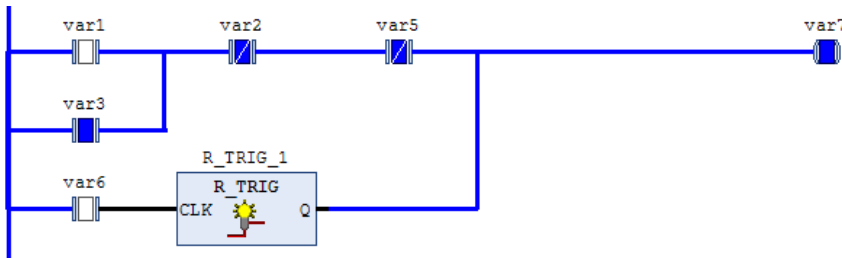
IF x[ 11 ] > 100 THEN
  x[ 12 ] := 0;
ELSIF x[ 11 ] > 50 THEN
  x[ 12 ] := x[ 12 ] + 2;
  inst1(a[ 111 ] := 111, b[ 222 ] := 222, c[ 333 ] := 333);
  inst1f(a[ 111 ] := 111, b[ 222 ] := 222, c[ 333 ] := 333);
ELSE
  x[ 12 ] := x[ 11 ] + 1;
  inst2(a[ 432 ] := 432, b[ 543 ] := 543, c[ 654 ] := 654);
  inst2f(a[ 432 ] := 432, b[ 543 ] := 543, c[ 654 ] := 654);
END_IF
    
```

## Switchable among FBD/LD/IL at a shortcut key

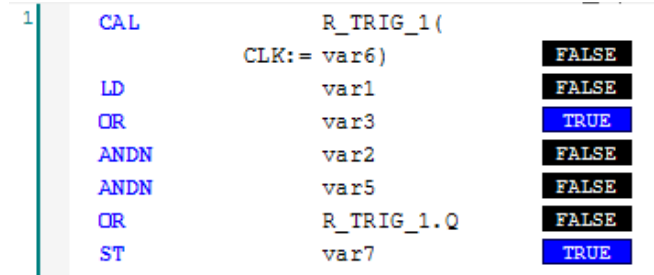
**FBD : [Ctrl] + [1]**



**LD : [Ctrl] + [2]**



**IL : [Ctrl] + [3]**

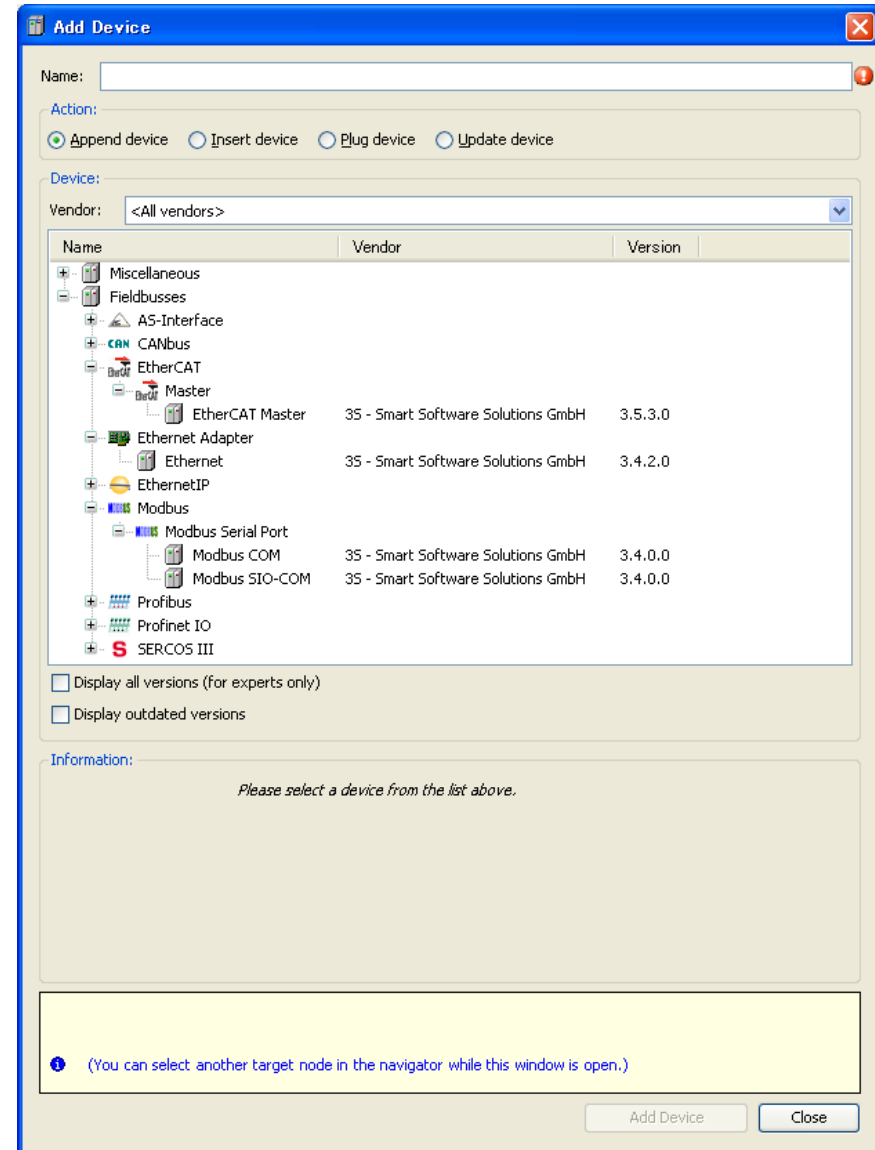


- EtherCAT master
- Modbus-TCP master
- Modbus-TCP slave
- Modbus-RTU master

EtherCAT			
Master			
EtherCAT Master	35 - Smart Software Solutions GmbH	3.5.3.0	

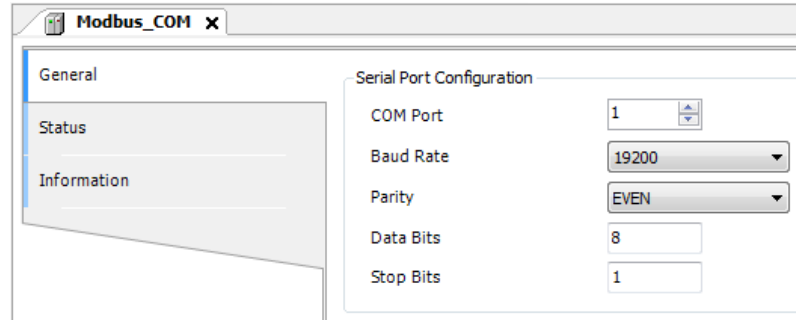
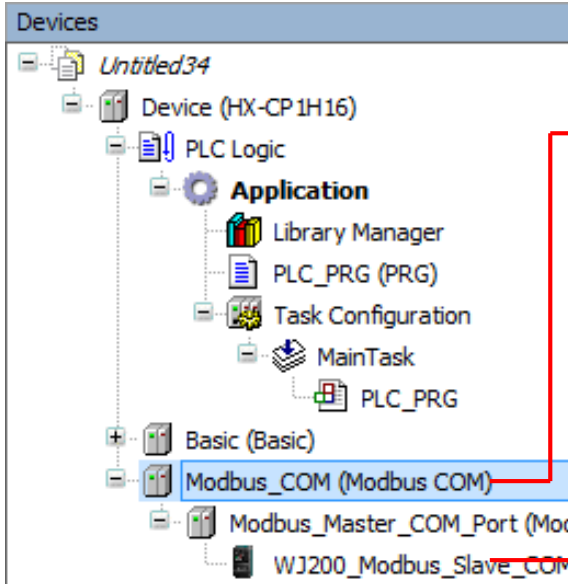
Modbus			
Modbus TCP Master			
Modbus TCP Master	35 - Smart Software Solutions GmbH	3.5.3.0	
ModbusTCP Slave Device			
ModbusTCP Slave Device	35 - Smart Software Solutions GmbH	3.5.2.0	

Modbus			
Modbus Serial Port			
Modbus COM	35 - Smart Software Solutions GmbH	3.4.0.0	
Modbus SIO-COM	35 - Smart Software Solutions GmbH	3.4.0.0	

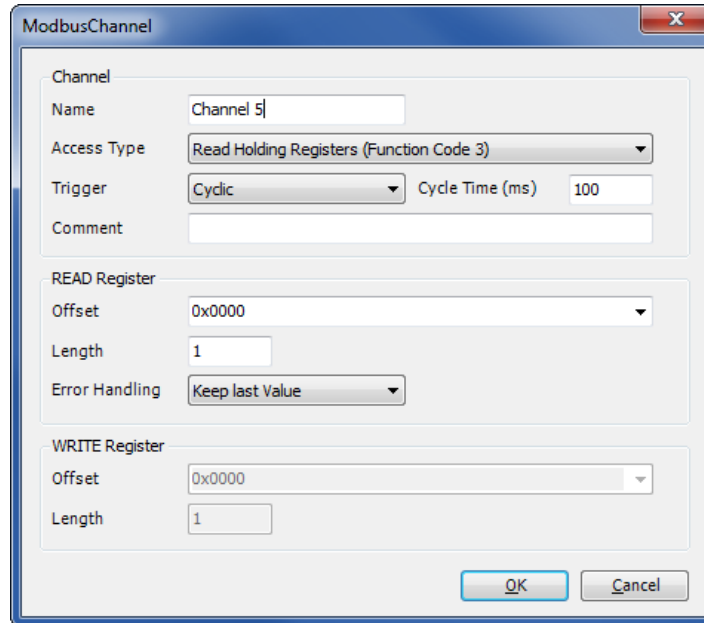


## Programless Modbus communication

### Ex) Modbus-RTU Master

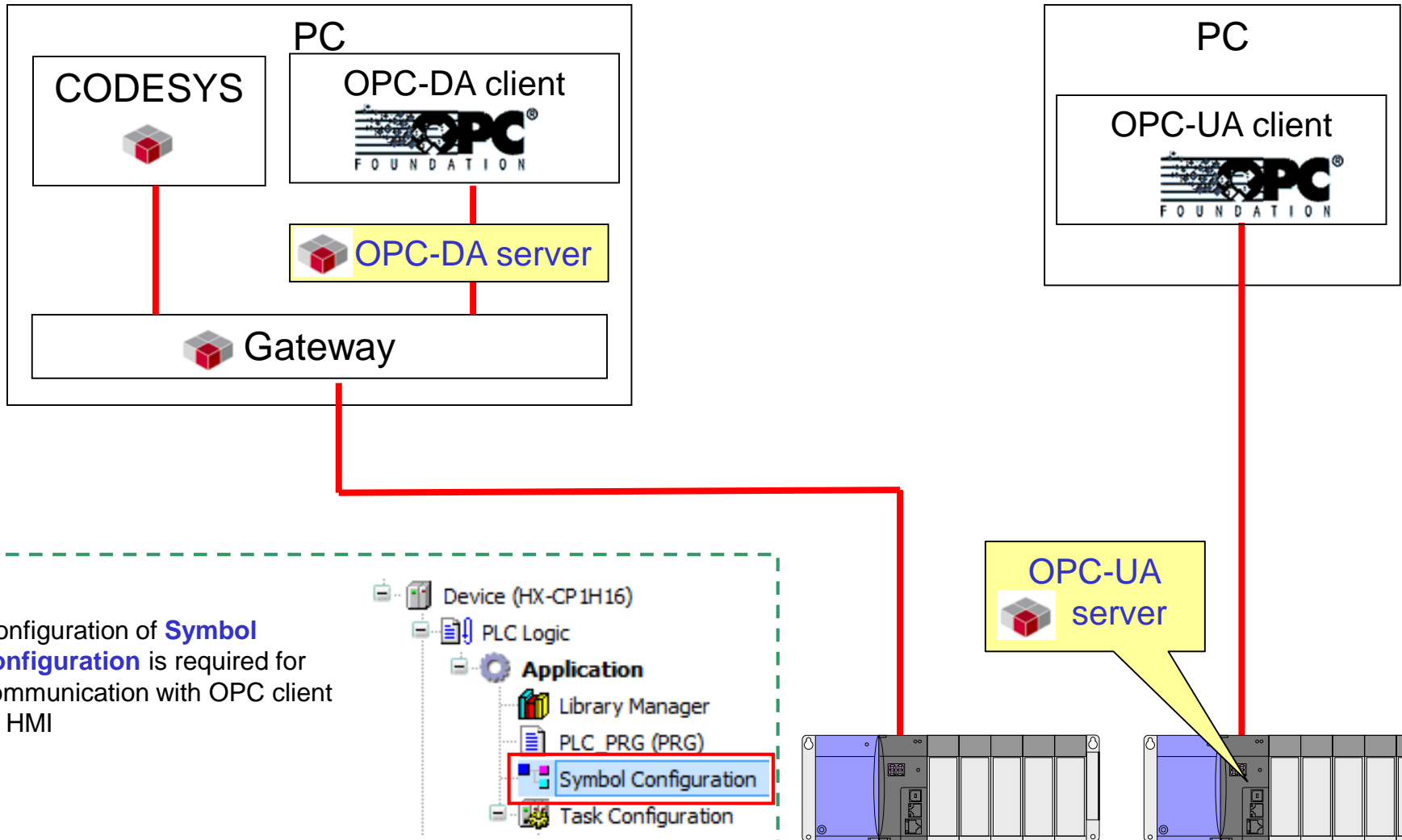


Communication setting



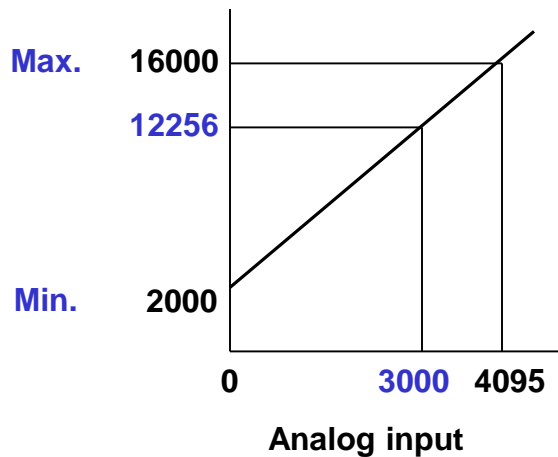
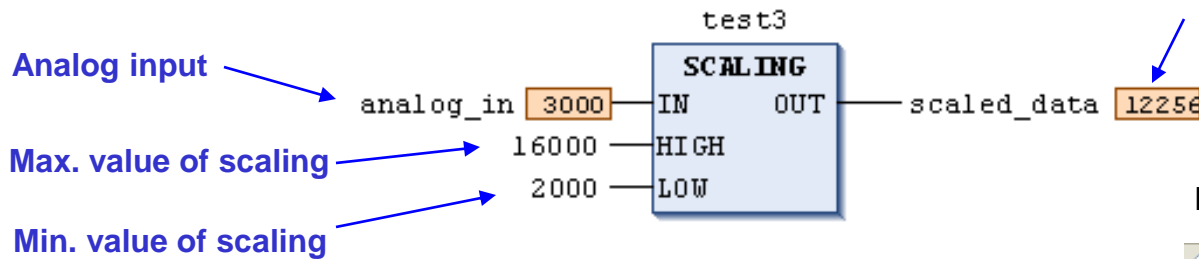
Read Holding register 0000 at 100ms cycle

## OPC-DA・OPC-UA communication



Frequently used program or function can be registered as library, which can be called from other projects.

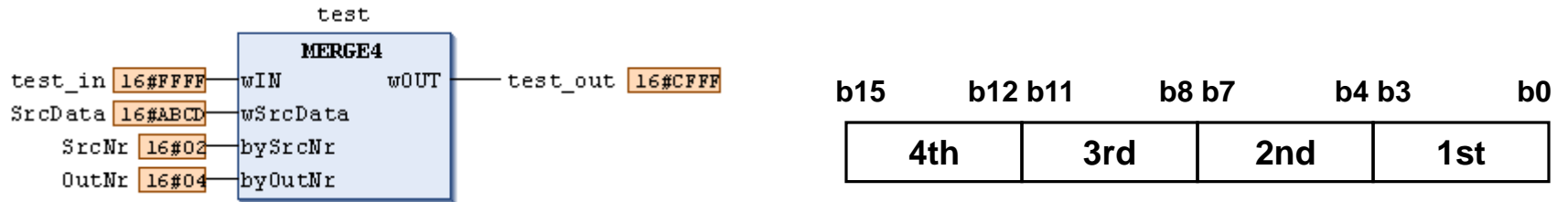
## Example 1: SCALING analog input value



## Program in the FB (possible to hide)

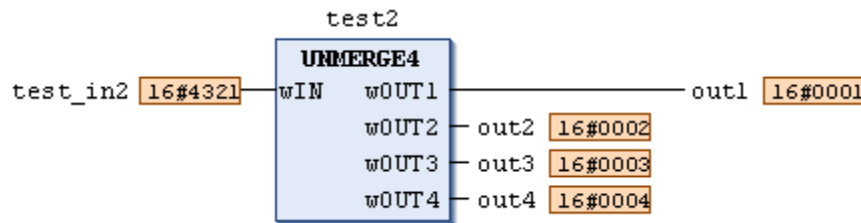
```
SCALING
1 FUNCTION_BLOCK SCALING
2 VAR_INPUT
3     IN: WORD;
4     HIGH: WORD;
5     LOW: WORD;
6 END_VAR
7 VAR_OUTPUT
8     OUT: WORD;
9 END_VAR
10 VAR
11     IIN: REAL;
12     IHIGH: REAL;
13     ILOW: REAL;
14     IOUT: REAL;
15 END_VAR
16
17 IIN:=WORD_TO_REAL(IN);
18 IHIGH:=WORD_TO_REAL(HIGH);
19 ILOW:=WORD_TO_REAL(LOW);
20 IOUT:= ((IHIGH - ILOW)/4095*IIN) + ILOW;
21 OUT:=REAL_TO_WORD(IOUT);
```

## Example 2: MERGE4



2<sup>nd</sup> 4bit data (“C”) of SrcData is written to 4<sup>th</sup> 4bit data of “test\_in”

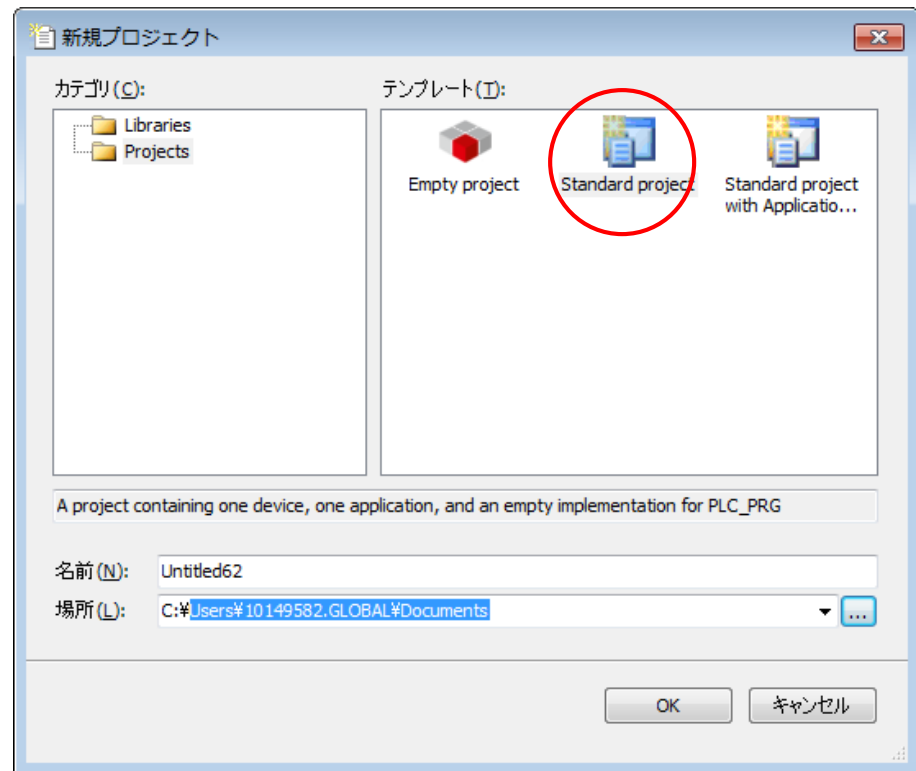
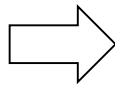
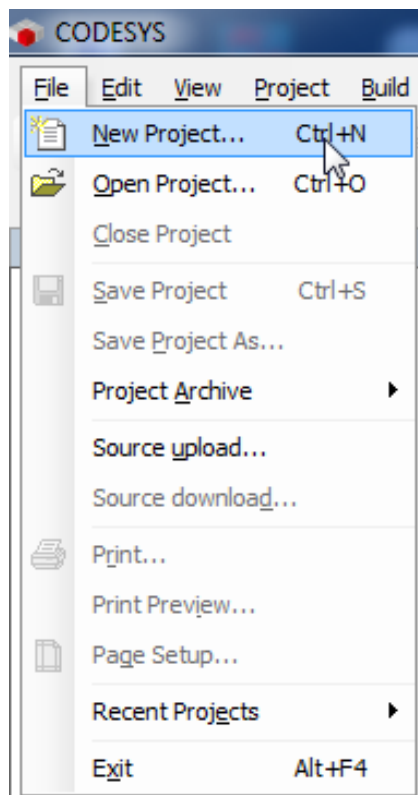
## Example 3: UNMERGE4



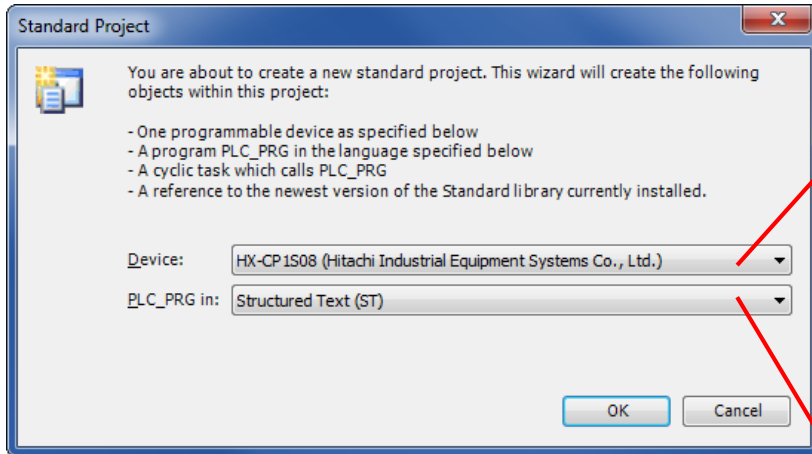
# Programming

1. Select [File] – [New Project] menu
2. Select [Standard project]

(Empty project: requires you adding all components manually)

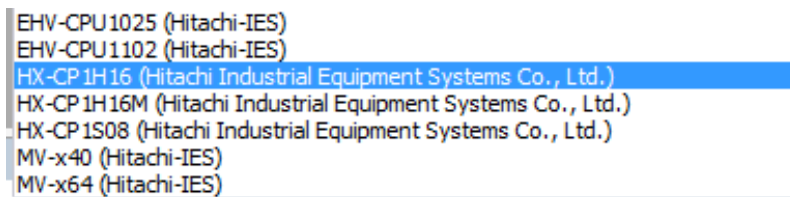


1. Select CPU type (This setting can be changed later)
2. Select programming language of default POU



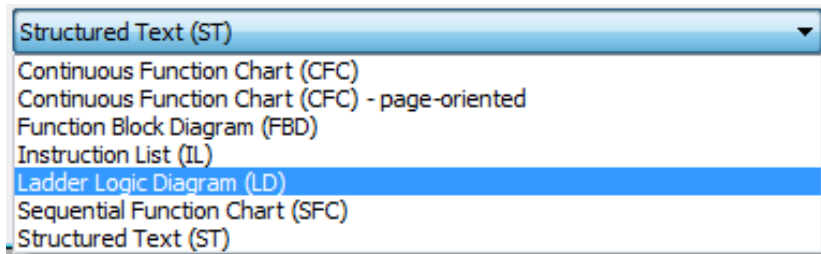
## CPU type

- HX-CP1S08
- HX-CP1H16
- EHV-CPU1102
- EHV-CPU1025
- CODESYS Control Win V3 (Soft PLC operates on PC)

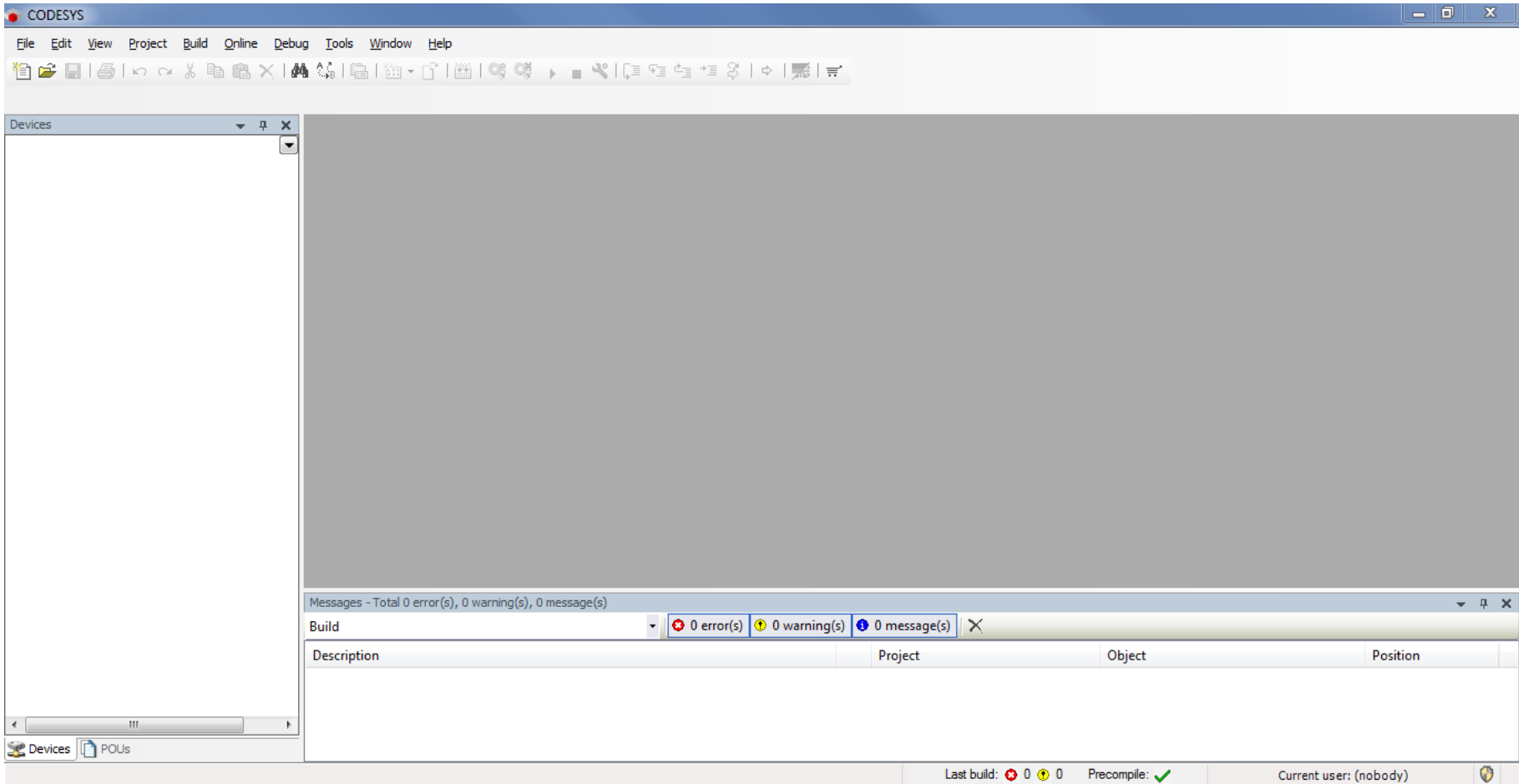


## Programming language

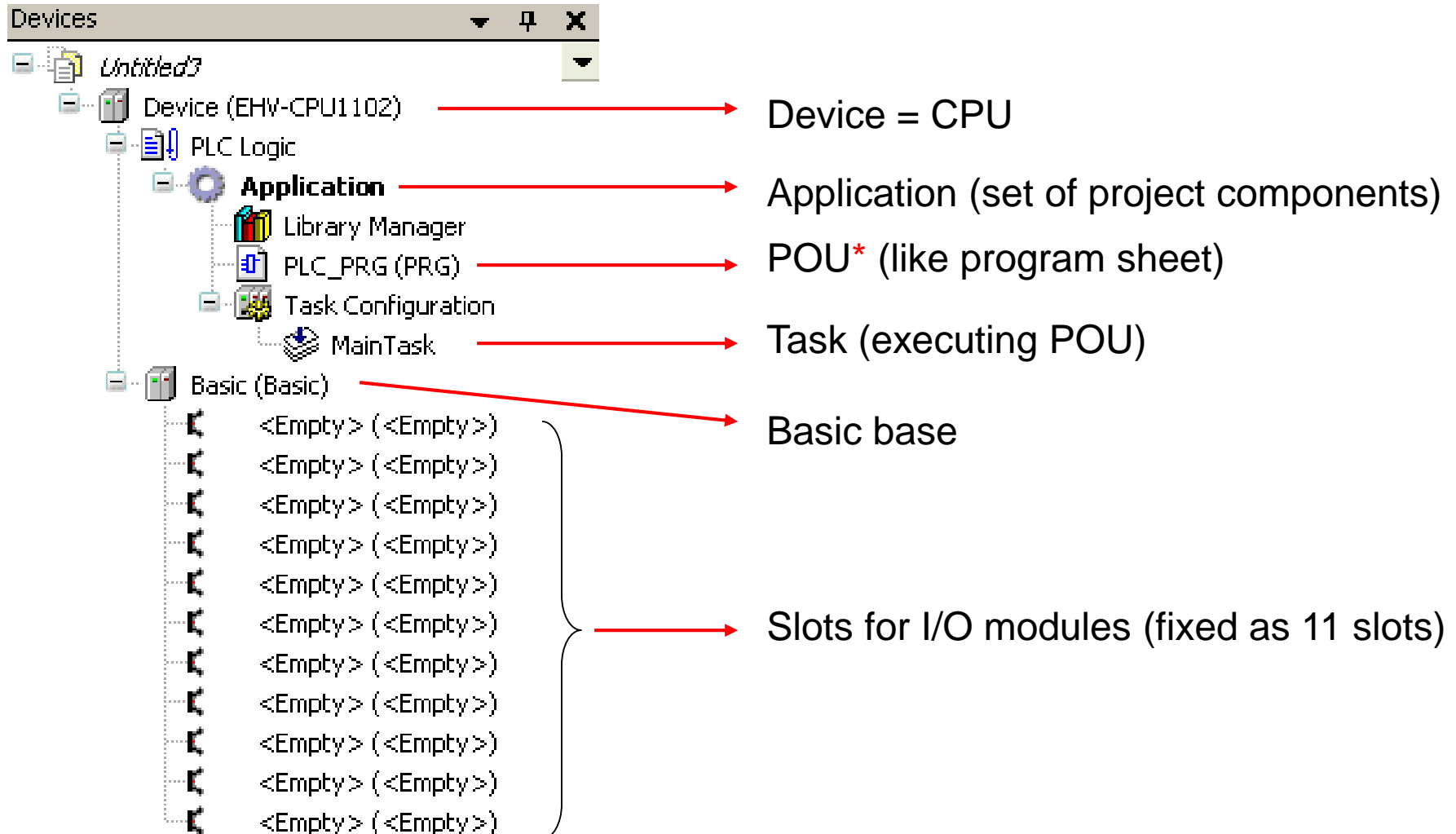
- CFC (Continuous Function Chart)
- FBD (Function Block Diagram)
- IL (Instruction List)
- LD (Ladder Logic Diagram)
- SFC (Sequential Function Chart)
- ST (Structured Text: Similar to C)



## Default window layout

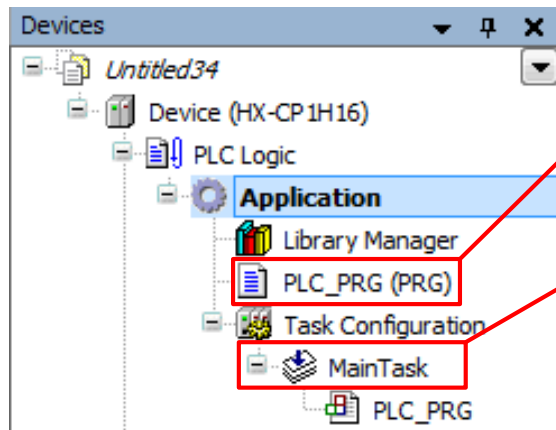


## Project Tree



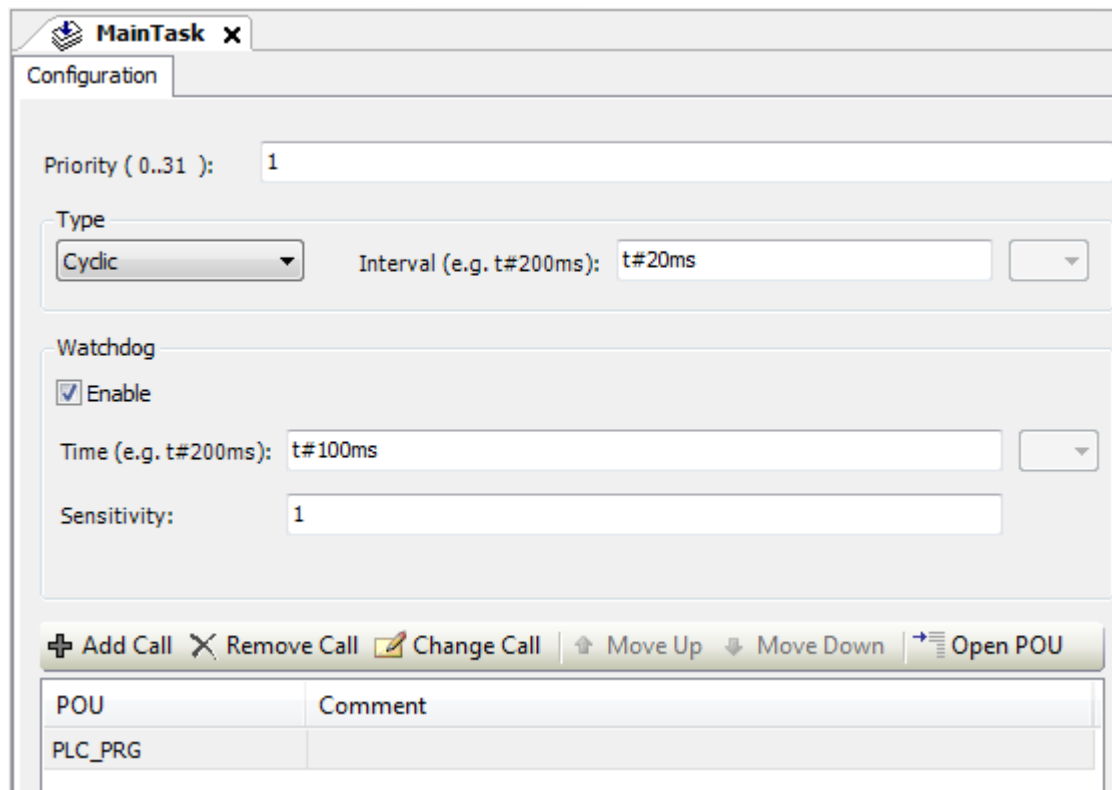
\* POU = Program Organization Unit

## Project tree



**POU:** User program

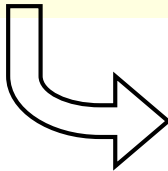
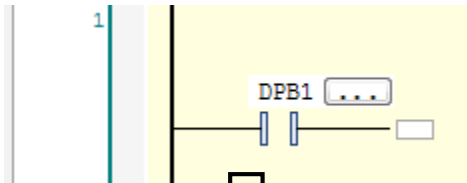
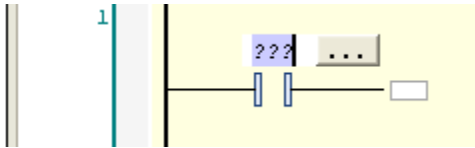
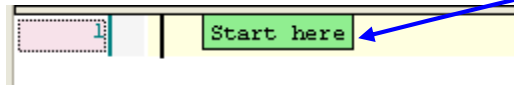
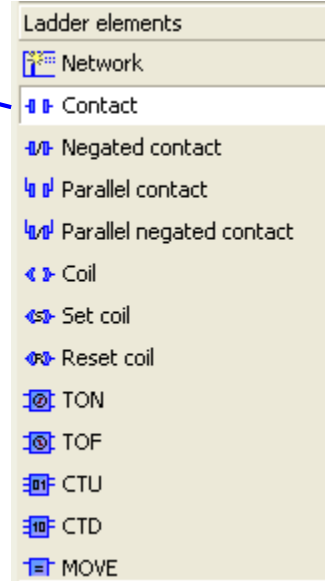
**Task:** Handles priority and execution cycle of POU



## Maximum number of Tasks: 49

Max. number of tasks: 49  
Max. number of cyclic tasks: 32  
Max. number of freewheeling tasks: 1  
Max. number of event tasks: 8  
Max. number of status tasks: 8

Drag "Contact" to **Start here**



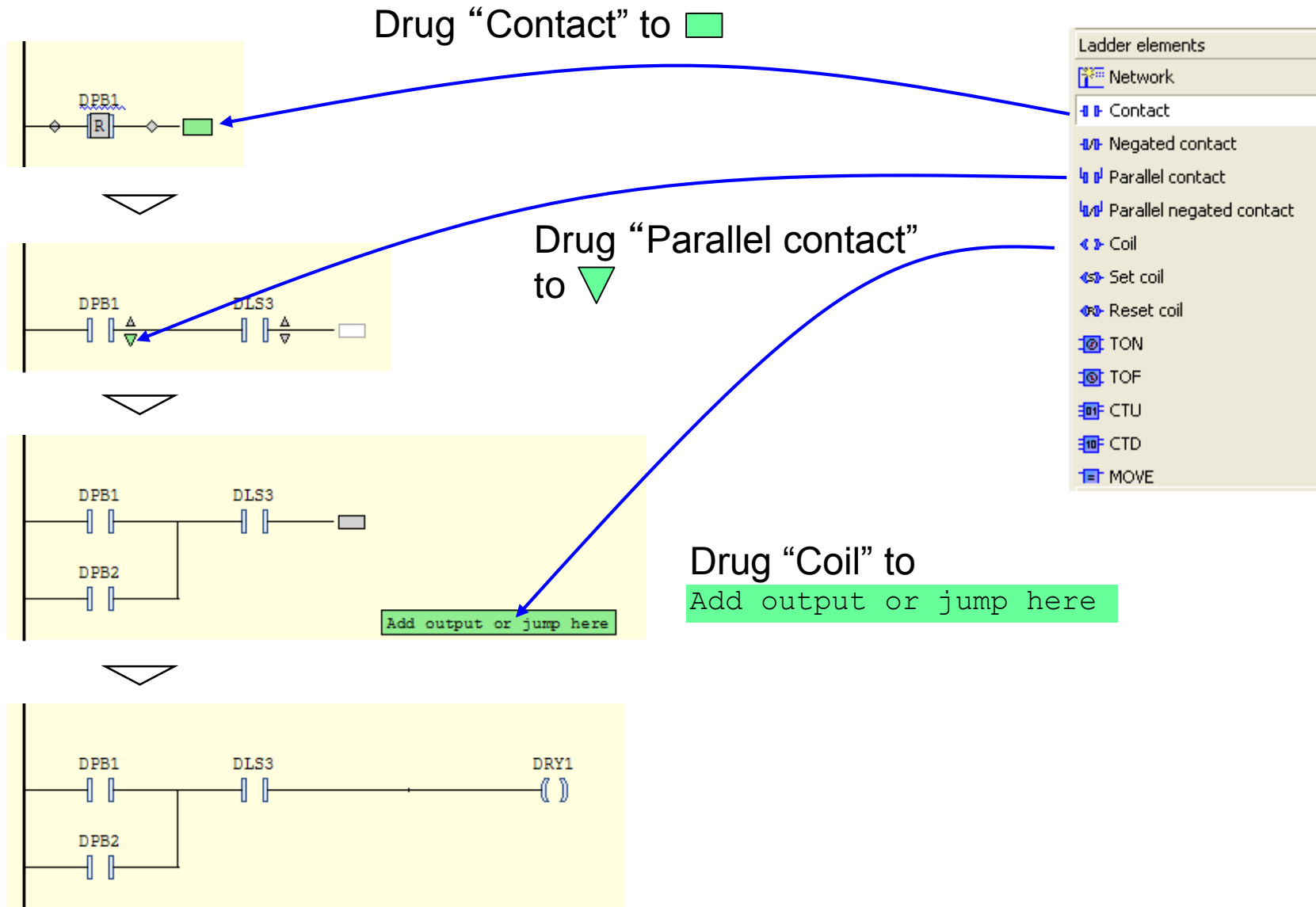
Type optional variable name

Declare window automatically appears

自動宣言

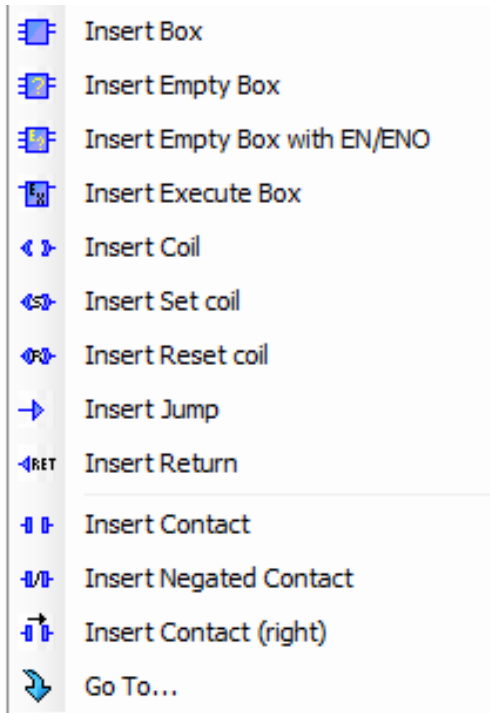
スコープ(S): VAR	名前(N): DPB1	型(T): BOOL
オブジェクト(O): PLC_PRG [Application]	初期値(I): ...	アドレス(A): 
フラグ(E): <input type="checkbox"/> 定数 [CONSTANT](C) <input type="checkbox"/> 保持 [RETAIN](R) <input type="checkbox"/> 持続 [PERSISTENT](P)	コメント(M): 	

OK キャンセル

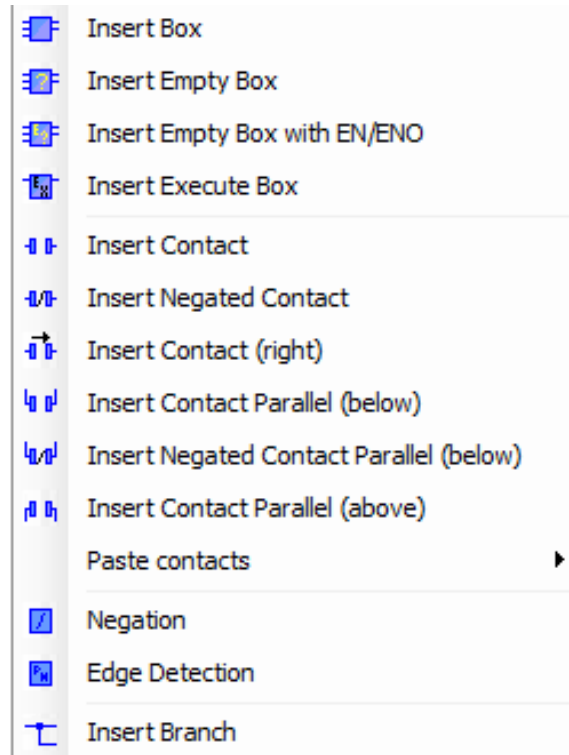


A symbol can also be inserted by right-clicking or shortcut keys.

Right-clicking  
in blank space of circuit.



Right-clicking  
on a Contact symbol.



A example of shortcut keys

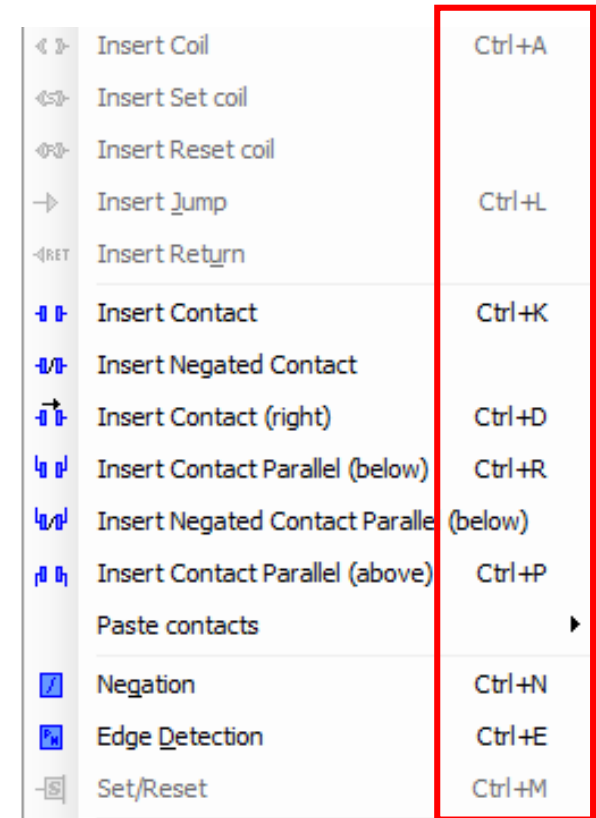
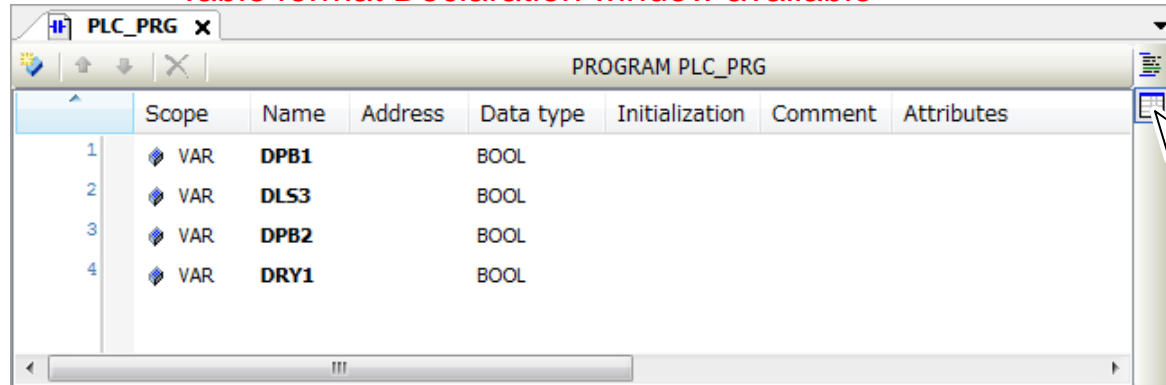
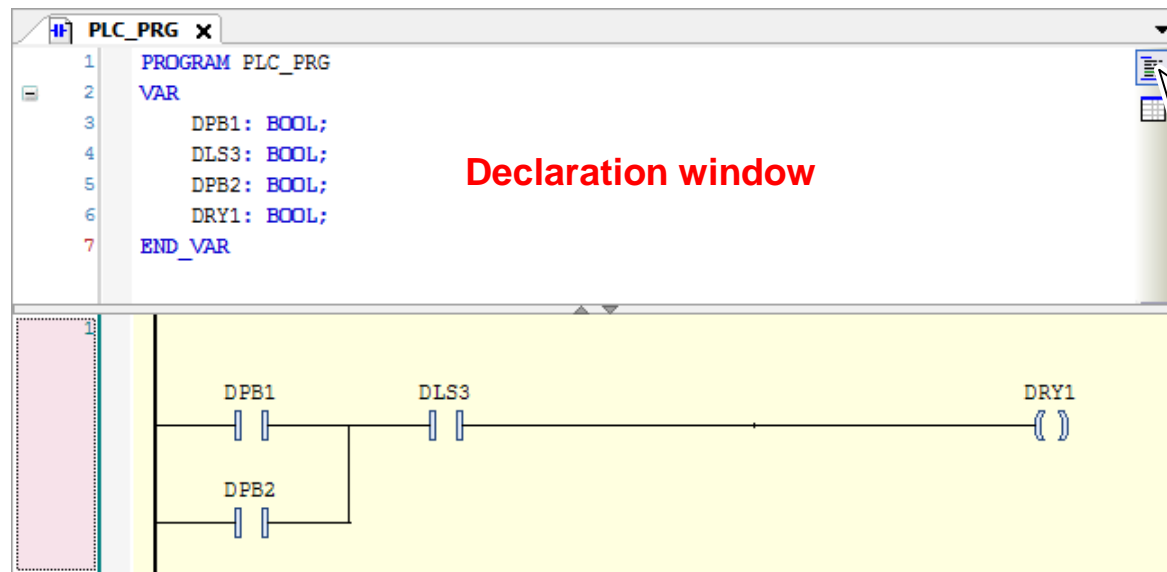


Table format Declaration window available



	Scope	Name	Address	Data type	Initialization	Comment	Attributes
1	VAR	DPB1		BOOL			
2	VAR	DLS3		BOOL			
3	VAR	DPB2		BOOL			
4	VAR	DRY1		BOOL			

Table format




Declaration window

Text format

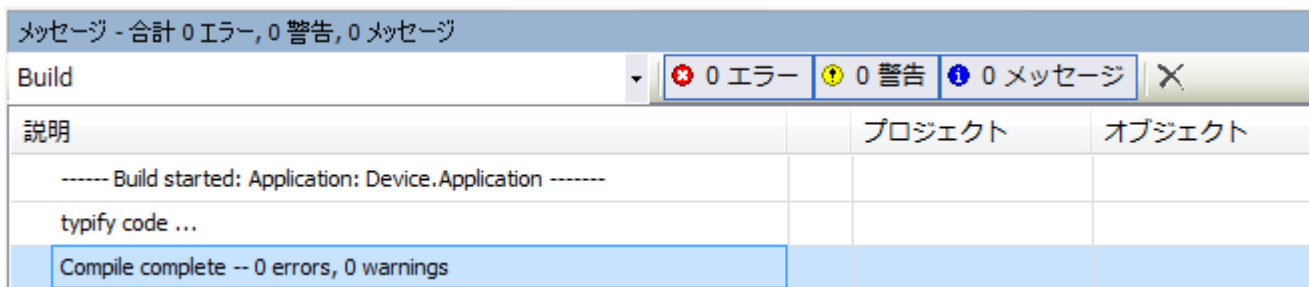
(Note) The variables declared in each POU are dealt as **local variables**.

# Brief Program (using internal I/O only)

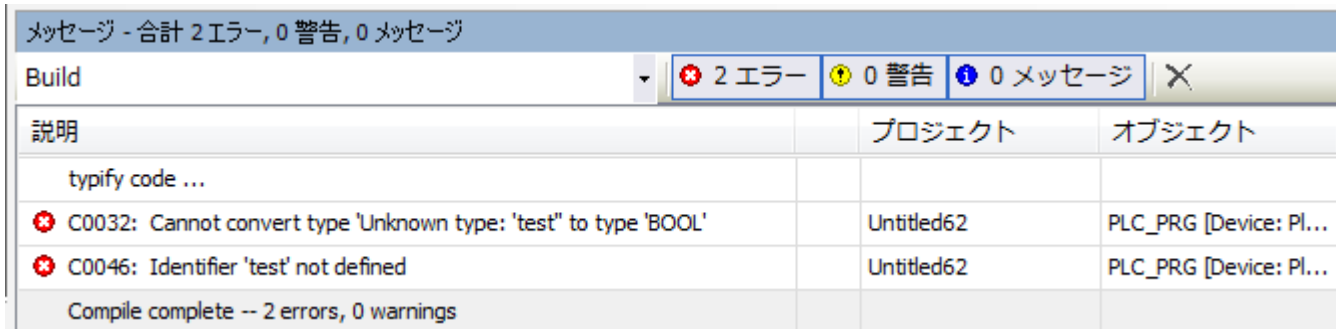
**Compile** the project by clicking **Build** after completing programming  
( icon or [F11] or menu [Build] - [Build])



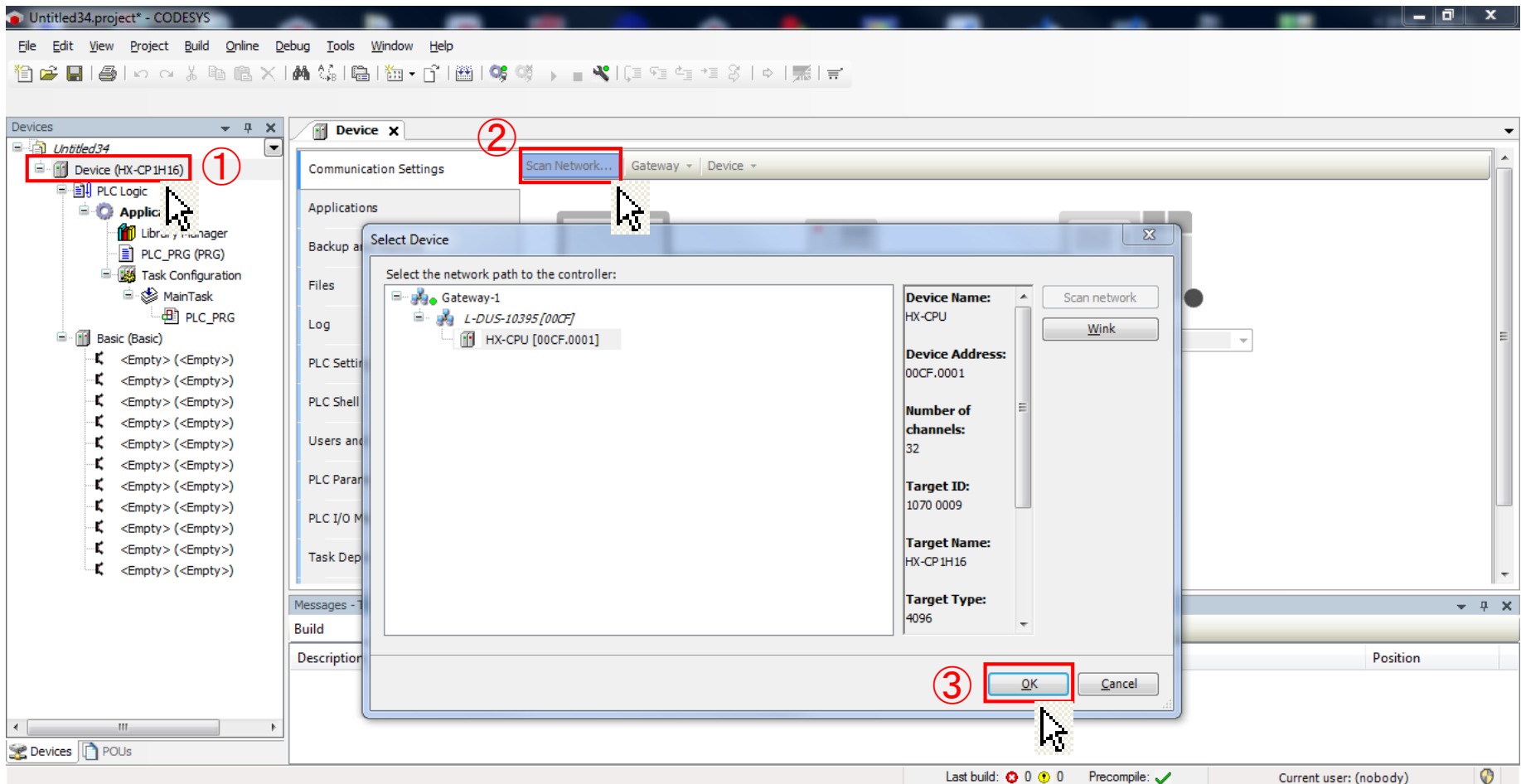
OK if no error is detected




Modify program if any error is detected



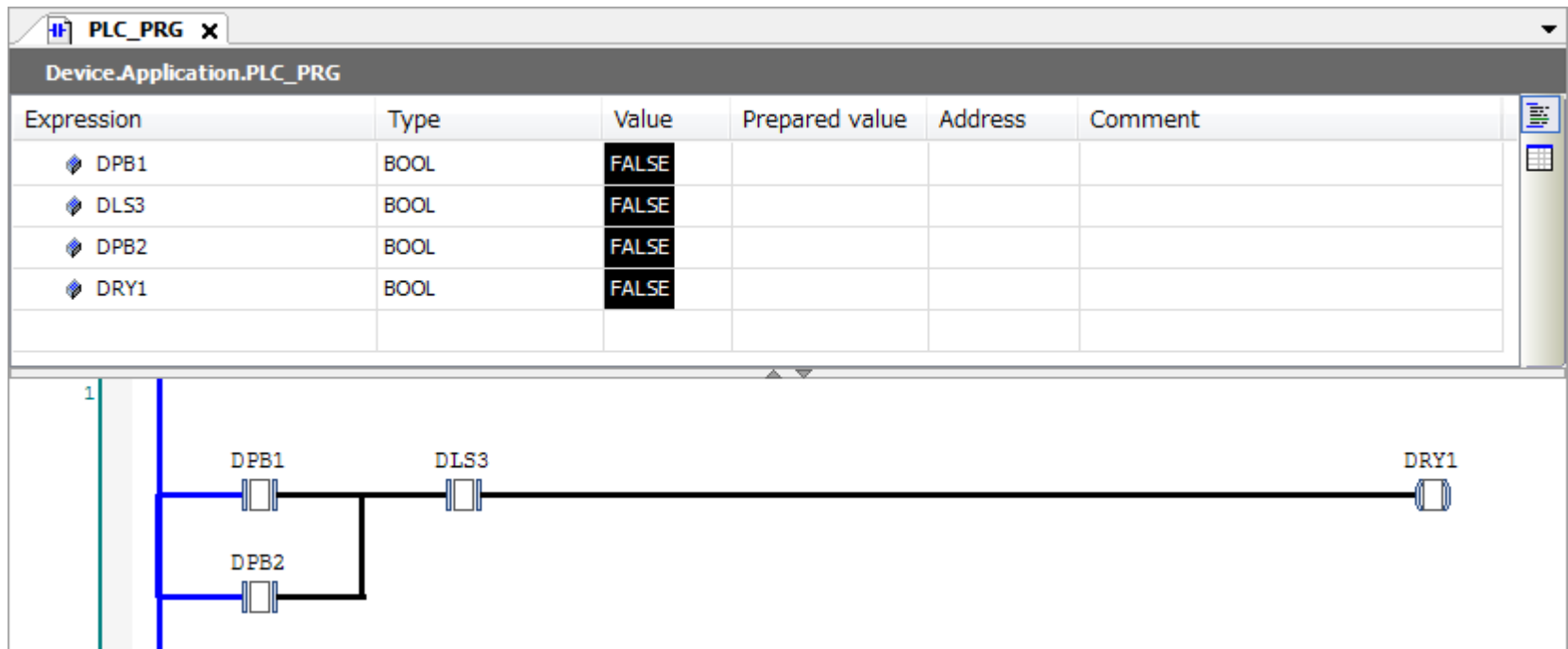
- ① Double-click “Device”
- ② Click [Scan network...]
- ③ Click [OK] on “Select Device” window after choosing the target device



Go Online by  icon or [Alt]+[F8] or menu [Online] – [Login]



Program is automatically **downloaded to PLC** when logging in and the window switches to **Online monitor**



The screenshot shows the 'Online monitor' window for 'Device.Application.PLC\_PRG'. It features a table of variables and a ladder logic diagram below it.

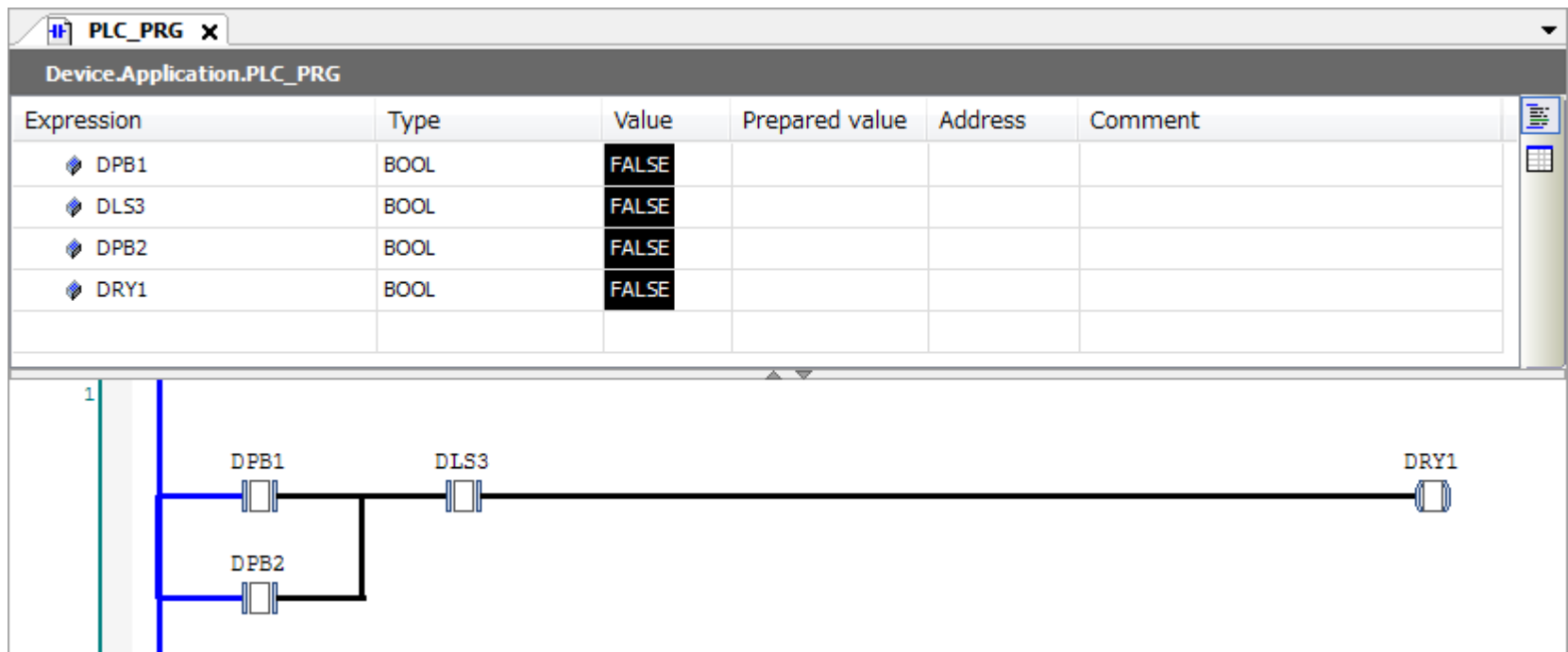
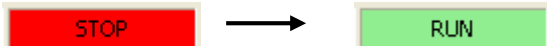
Expression	Type	Value	Prepared value	Address	Comment
DPB1	BOOL	FALSE			
DLS3	BOOL	FALSE			
DPB2	BOOL	FALSE			
DRY1	BOOL	FALSE			

Below the table is a ladder logic diagram. It shows a power rail on the left with two normally open contacts labeled 'DPB1' and 'DPB2' connected in parallel. This parallel combination is connected to a normally open contact labeled 'DLS3'. The output of 'DLS3' is connected to a coil labeled 'DRY1'.

# Commissioning (Write value)

Run

Run by  icon or [F5] or menu [Debug] – [Start]



The screenshot shows a software window titled "PLC\_PRG" with a sub-window "Device.Application.PLC\_PRG". It contains a table of variable declarations and a ladder logic diagram below it.

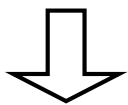
Expression	Type	Value	Prepared value	Address	Comment
DPB1	BOOL	FALSE			
DLS3	BOOL	FALSE			
DPB2	BOOL	FALSE			
DRY1	BOOL	FALSE			

The ladder logic diagram shows a network with a vertical bus on the left. Two normally open contacts, DPB1 and DPB2, are connected in parallel to the bus. This parallel combination is connected to a normally open contact DLS3. The output of DLS3 is connected to a coil (output) labeled DRY1.

# Commissioning (Write value)

Expression	Type	Value	Prepared value	Address	Comment
DPB1	BOOL	FALSE	TRUE		
DLS3	BOOL	FALSE	TRUE		
DPB2	BOOL	FALSE			
DRY1	BOOL	FALSE			


① Prepare TRUE by double-clicking DPB1, DLS3

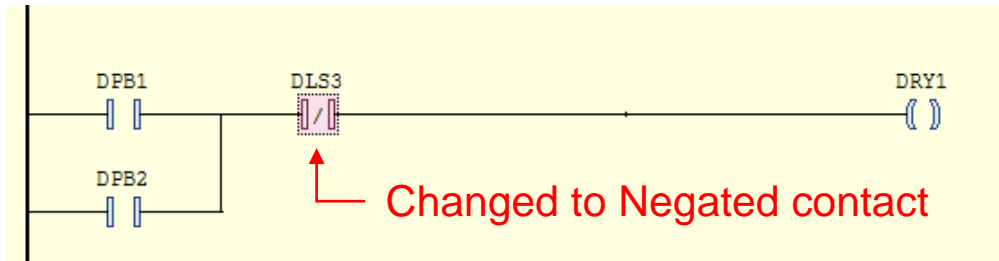


② Apply the prepared value for PLC by [Ctrl]+[F7] or menu [Debug] - [Write value]

Expression	Type	Value	Prepared value	Address	Comment
DPB1	BOOL	TRUE			
DLS3	BOOL	TRUE			
DPB2	BOOL	FALSE			
DRY1	BOOL	TRUE			

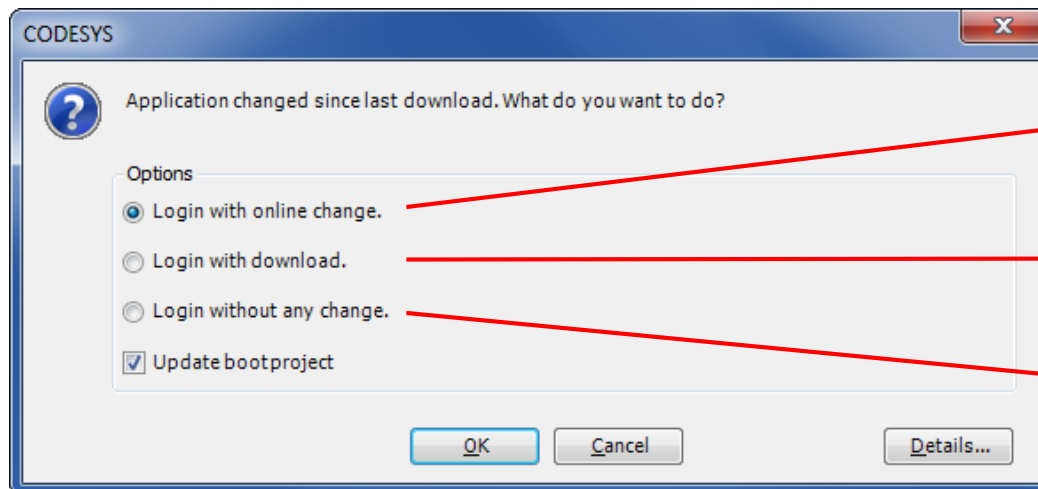
## Procedure

1.  Logout (Off line)
2. Change program



3.  Login (Online)

Select "Login with online change"



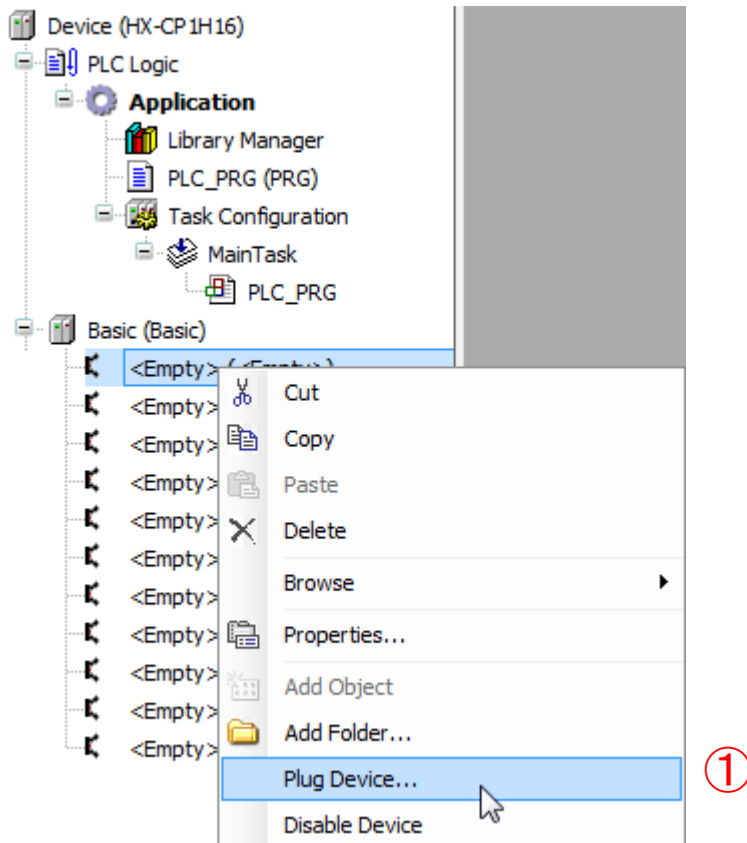
Online change

Program download  
(CPU stops while downloading)

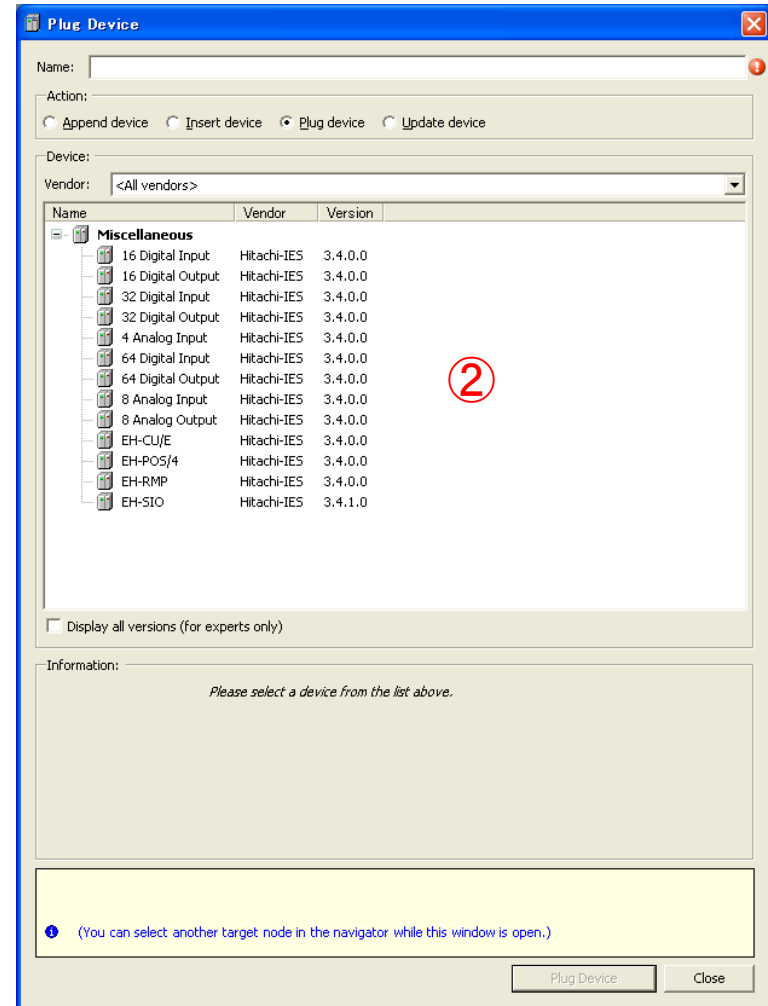
Login without changing

## I/O assignment (Manual configuration)

① Select [Plug Device] after right-clicking a target empty slot under “Basic”

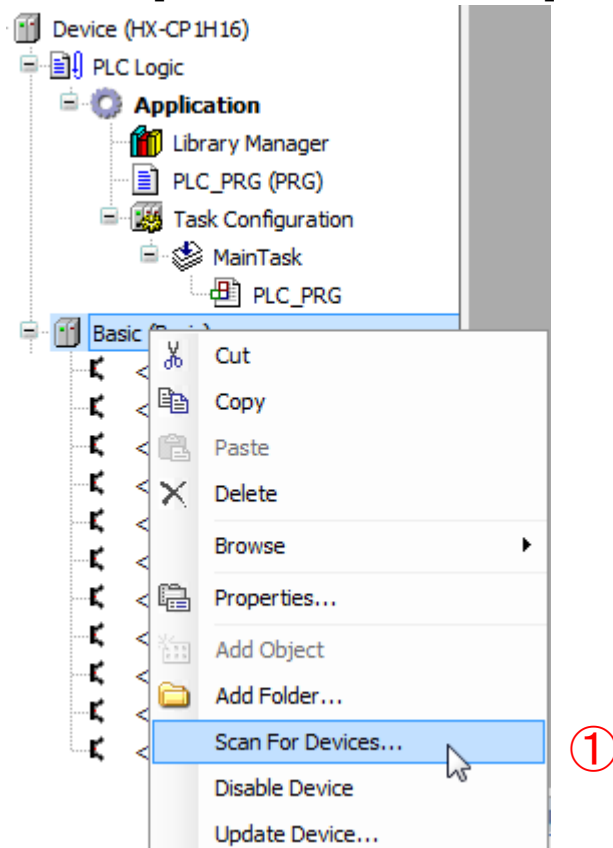


② Select I/O module at Plug Device window  
(continuous configuration without closing the dialog available)



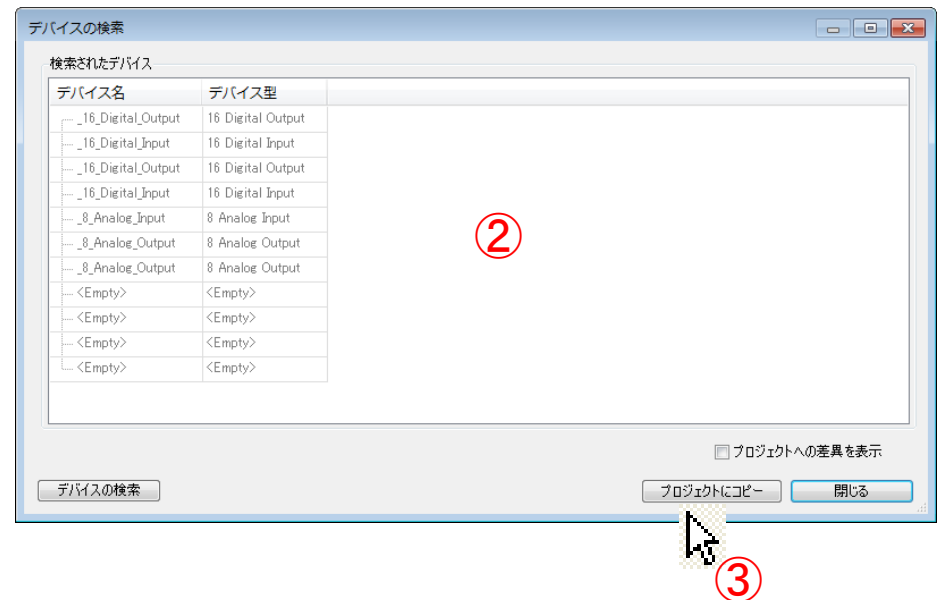
## I/O assignment (Scan Device)

① Select [Scan For Devices] after right-clicking “Basic”



② I/O modules mounted on base are detected

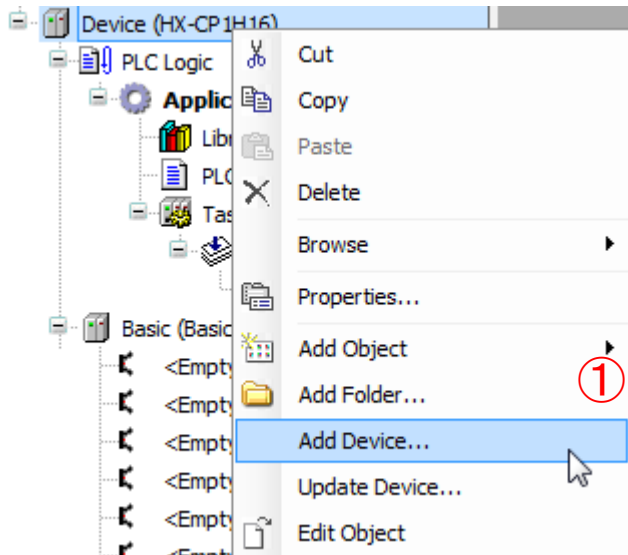
③ Click [Copy All Devices to Project]



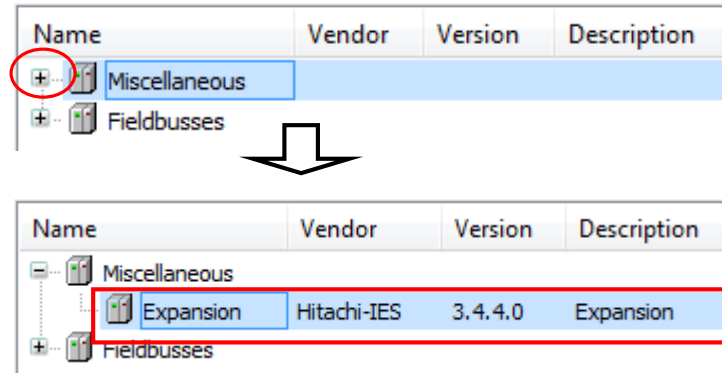
(Note) Scan For Devices is available while Off-line and works once going online to PLC.

## I/O assignment (Expansion unit)

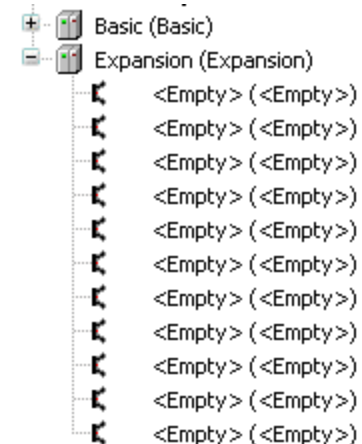
① Select [Add Device] after right-clicking “Device”



② Click [+] on “Miscellaneous”



③ Double-click “Expansion”



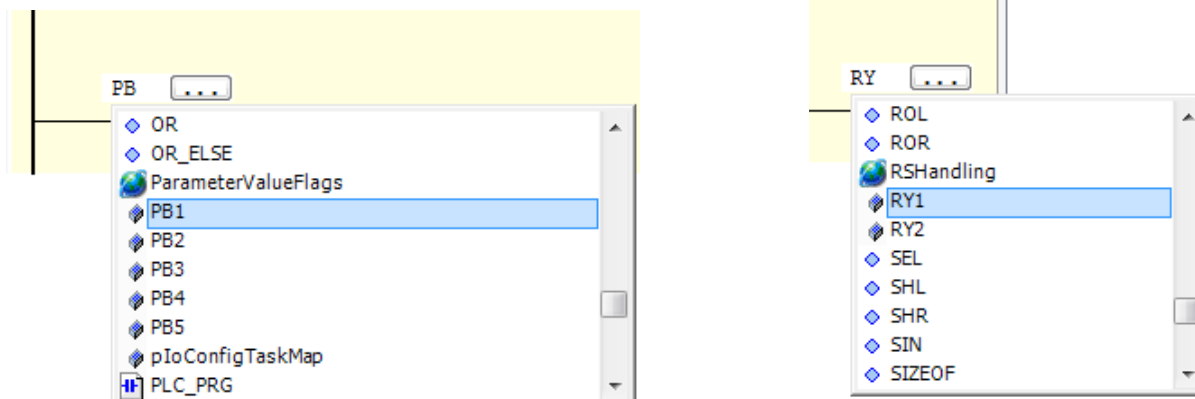
(Note) “Scan For Devices” is valid within its base unit.

It is required to operate “Scan For Devices” for each base unit when using expansion units.

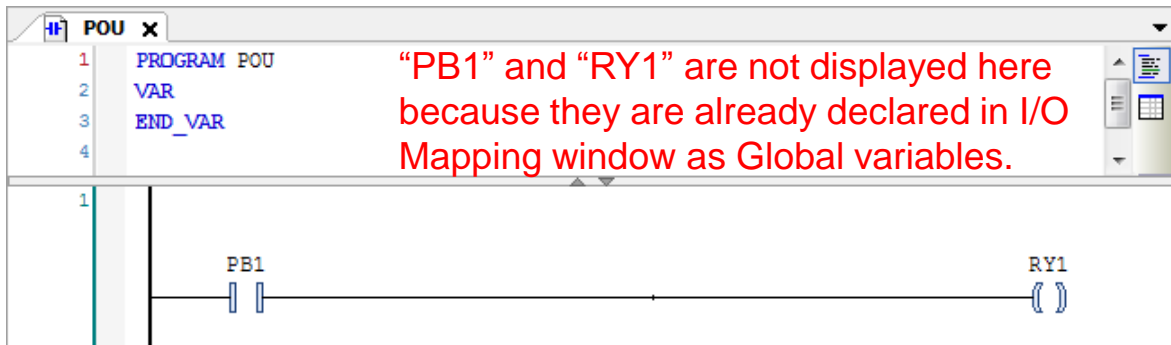


## Programming with the use of External I/Os

- Global variables are listed in Intellisense when typing initial letter.
- Select the one and ENTER



The image shows two Intellisense windows. The left window is for 'PB' and lists variables including OR, OR\_ELSE, ParameterValueFlags, PB1, PB2, PB3, PB4, PB5, pIoConfigTaskMap, and PLC\_PRG. The right window is for 'RY' and lists variables including ROL, ROR, RSHandling, RY1, RY2, SEL, SHL, SHR, SIN, and SIZEOF.

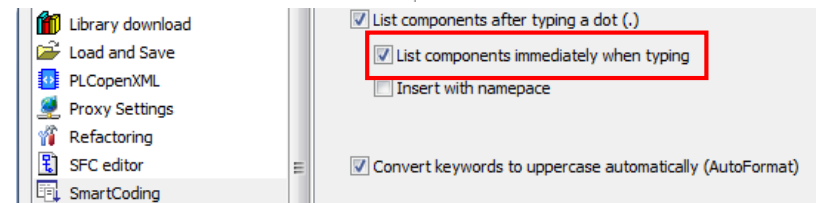


The screenshot shows a PLC program editor with a program named 'POU'. The program code is:

```
1 PROGRAM POU
2 VAR
3 END_VAR
```

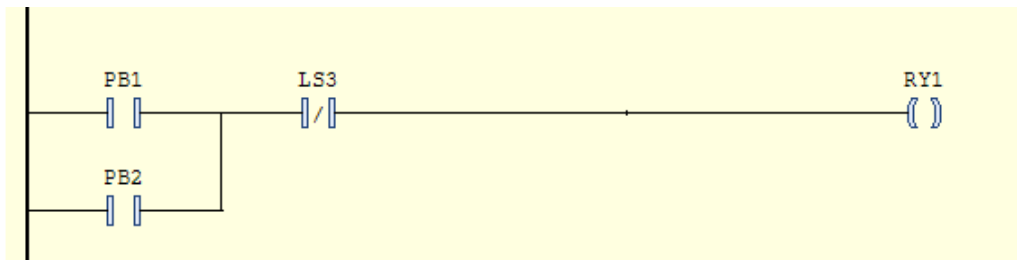
The ladder logic diagram shows a normally open contact labeled 'PB1' connected to a coil labeled 'RY1'. A red text box overlaid on the program editor states: "PB1" and "RY1" are not displayed here because they are already declared in I/O Mapping window as Global variables.

※ Intellisense can be activate/deactivate by configuring  
“List components immediately when typing” option in  
[Tool] - [Option] - [SmartCoding]



The screenshot shows the SmartCoding options menu. The option "List components immediately when typing" is checked and highlighted with a red box. Other options include "List components after typing a dot (.)", "Insert with namespace", and "Convert keywords to uppercase automatically (AutoFormat)".

## Programming with the use of External I/Os



### ■ 16 Digital Input

**\_16\_Digital\_Input**

Digital Input 16 I/O Mapping

Information

Status

Variable	Mapping	Channel
PB1		Bit0
PB2		Bit1
		Bit2
		Bit3
		Bit4
LS3		Bit5

### ■ 16 Digital Output

**\_16\_Digital\_Output**

16 Digital Output I/O Mapping

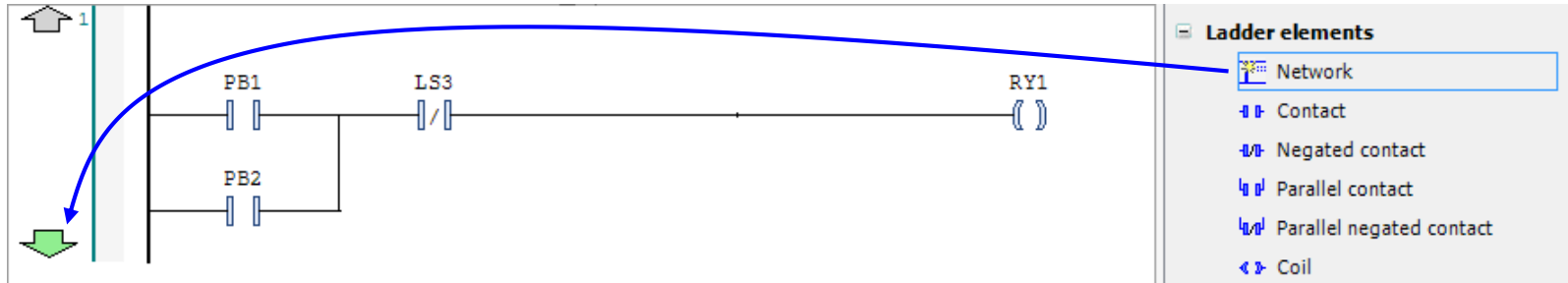
Information

Status

Variable	Mapping	Channel
RY1		Bit0
RY2		Bit1
		Bit2
		Bit3

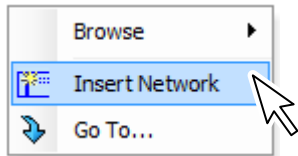
Let's download program and RUN CPU!

## Insert Line



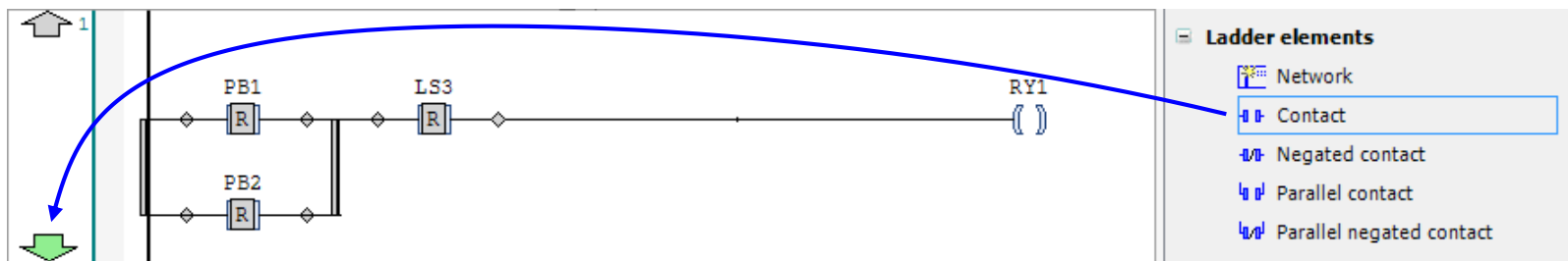
Drag "Network" to 

## Insert Line (Another way 1)



Click [Insert Network] after right-clicking blank space of program editor window

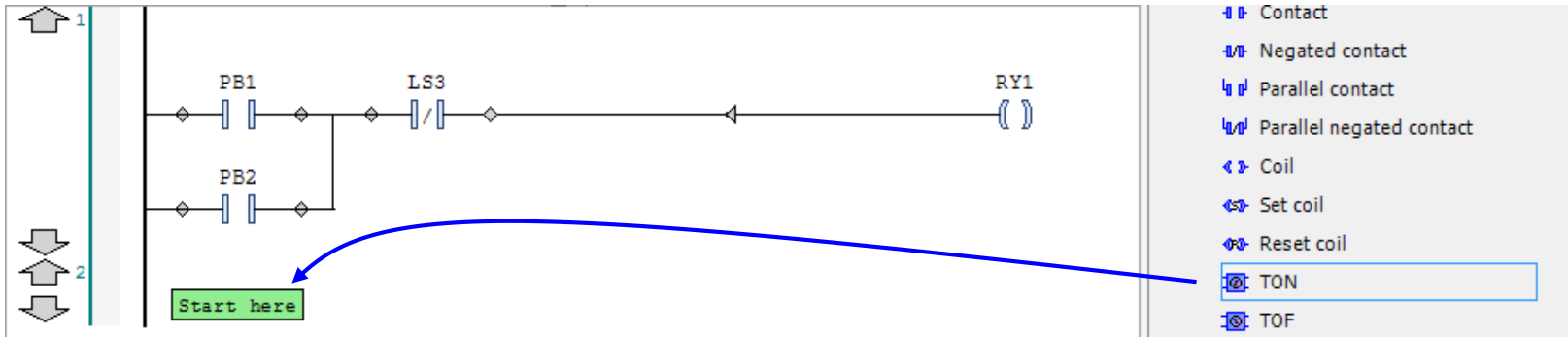
## Insert Line (Another way 2)



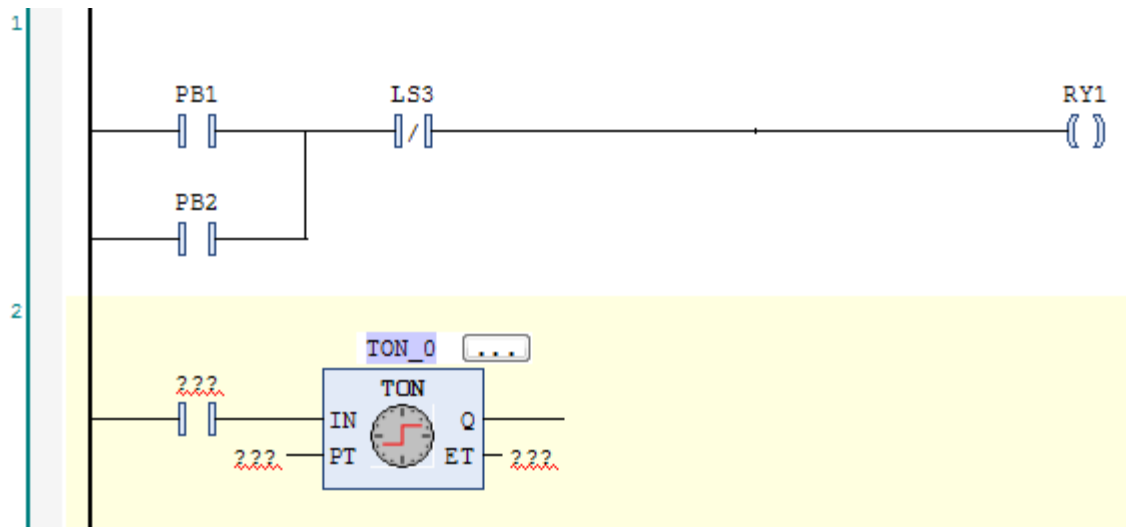
Drag a symbol you would like to add to next line to 

# Add FunctionBlock (timer)

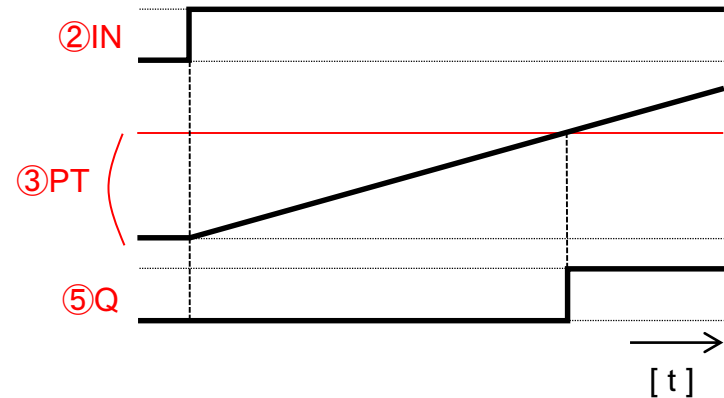
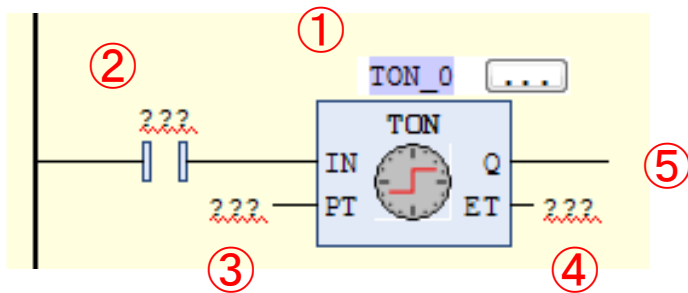
## Add "On delay timer"



Drag "TON" to **Start here**



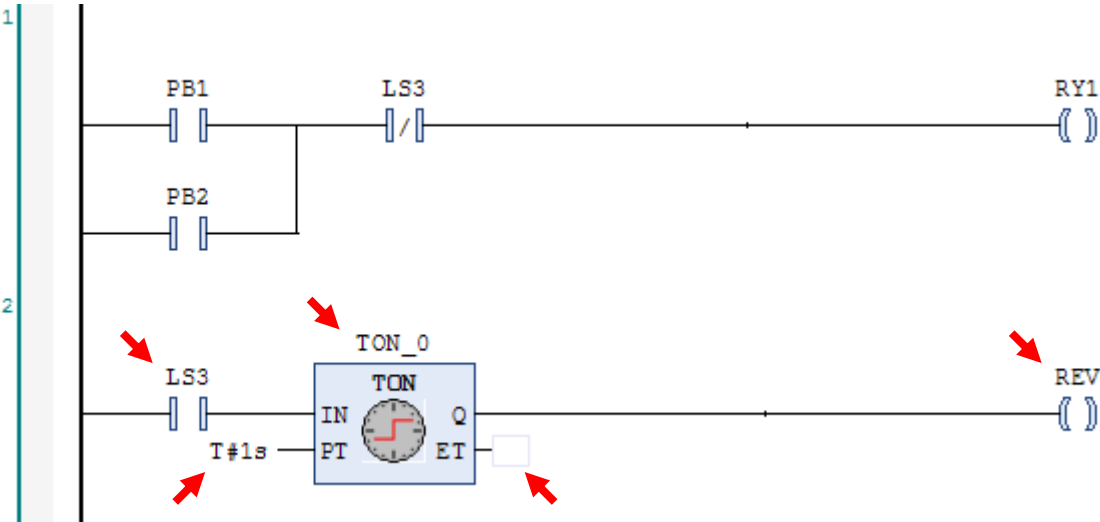
## Add “On delay timer”



- ① FunctionBlock needs a identifier (instance).
- ② [input] IN: Rising edge starts counting up ET.
- ③ [input] PT: Upper limit for counting up ET (delay time).  
(\* Example: T#10s)
- ④ [output] ET: current state of delay time.
- ⑤ [output] Q: Gets a rising edge as soon as ET has reached the upper limit PV (delay time is over).

# Add FunctionBlock (timer)

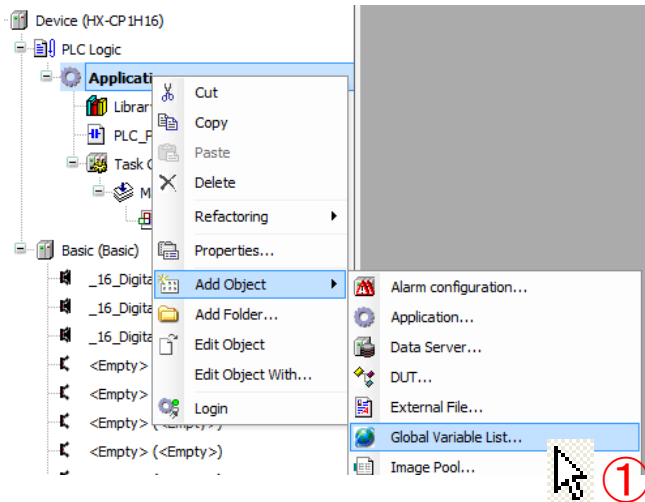
Add "On delay timer"



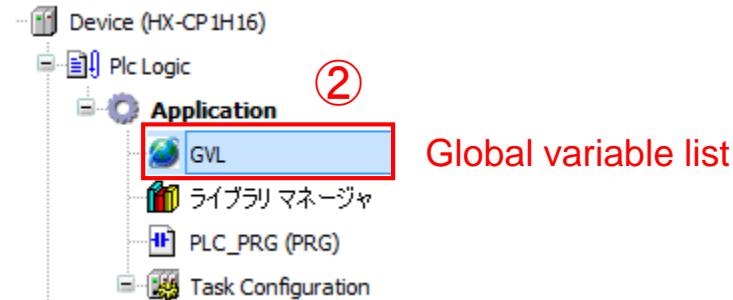
**Local variables** which are declared in each POU are **valid only in the POU**

**Global variables** can be accessed **from all POU**s in a project

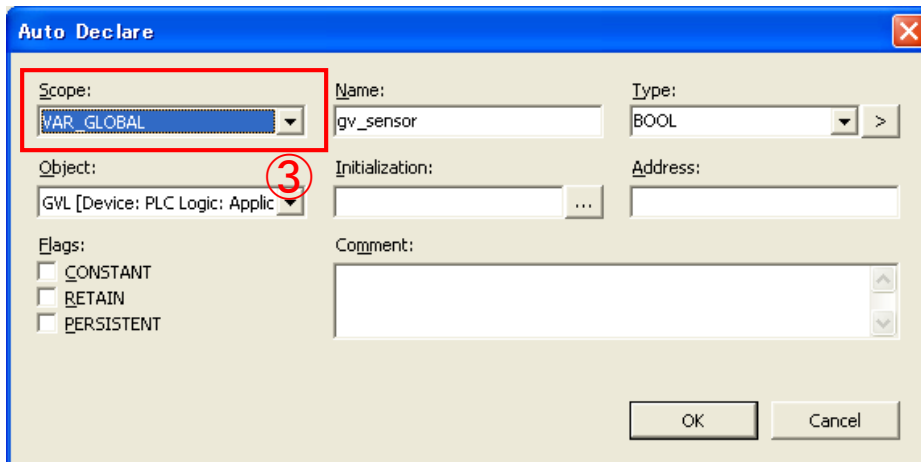
① Select [Add Object] - [Global Variable List] after right-clicking “Application”



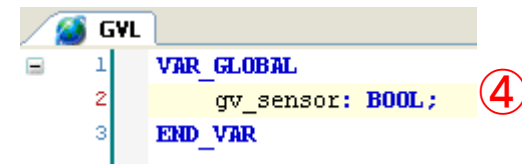
② Global variable list is added to the project



③ Select “VAR\_GLOBAL” at Scope when declaring a variable



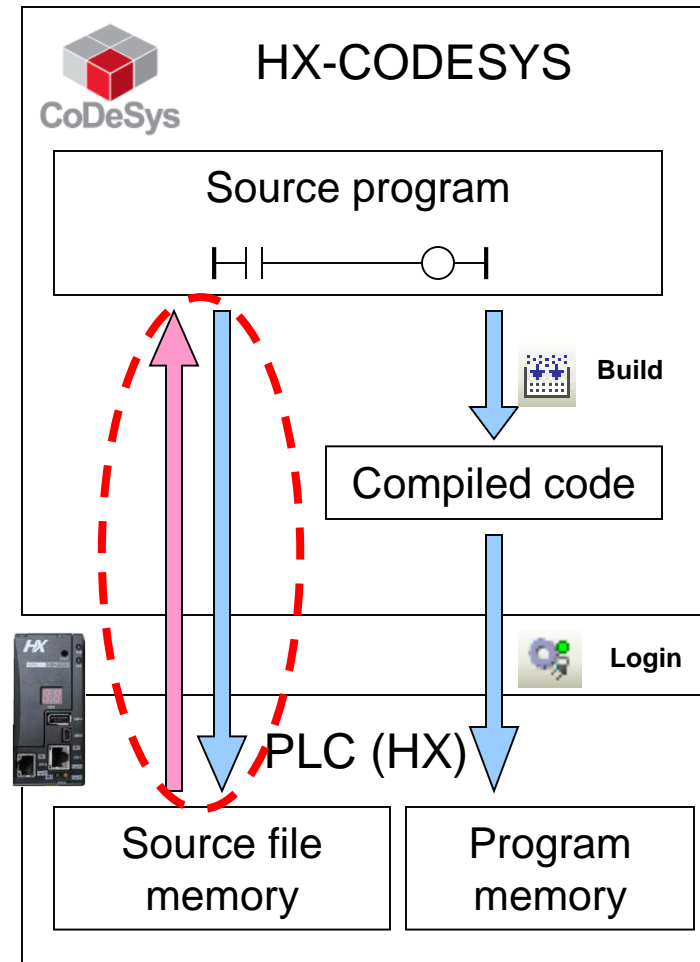
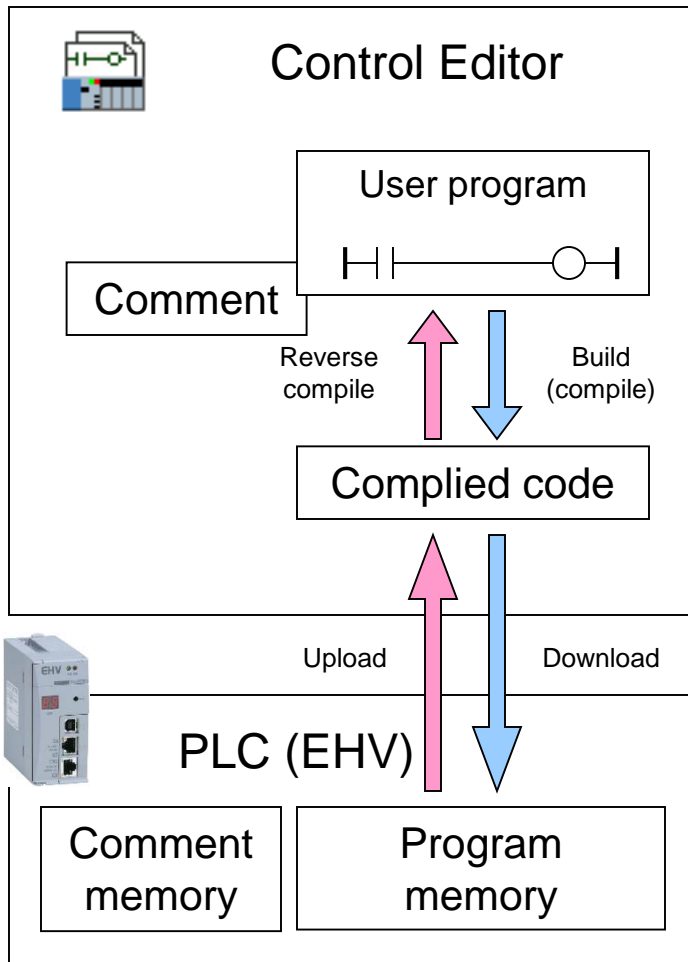
④ The variable is registered to GVL



⑤ put “GVL.” when programming  
Ex) `GVL.gv_sensor`

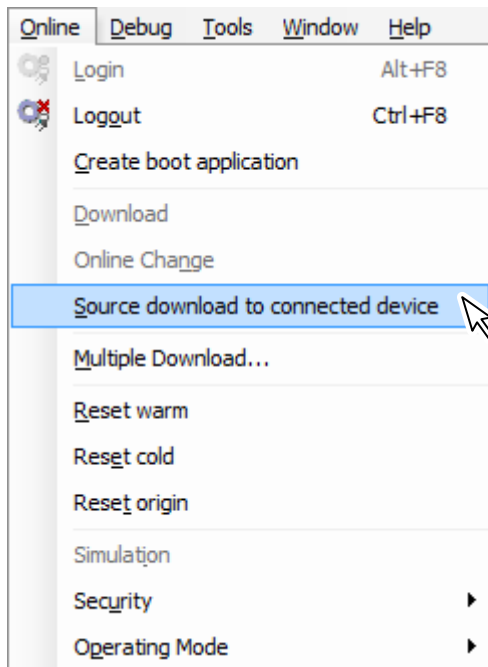
# Differences between Hitachi PLC and CODESYS PLC

## Flow of program up/downloading

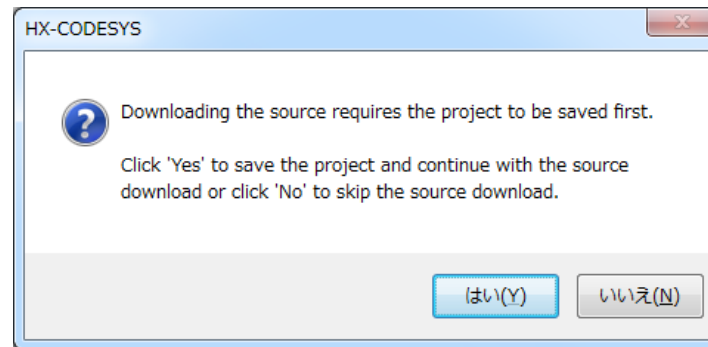


## Source download

- ① Go Online by [Login]
- ② Click [Online]-[Source download to connected device]

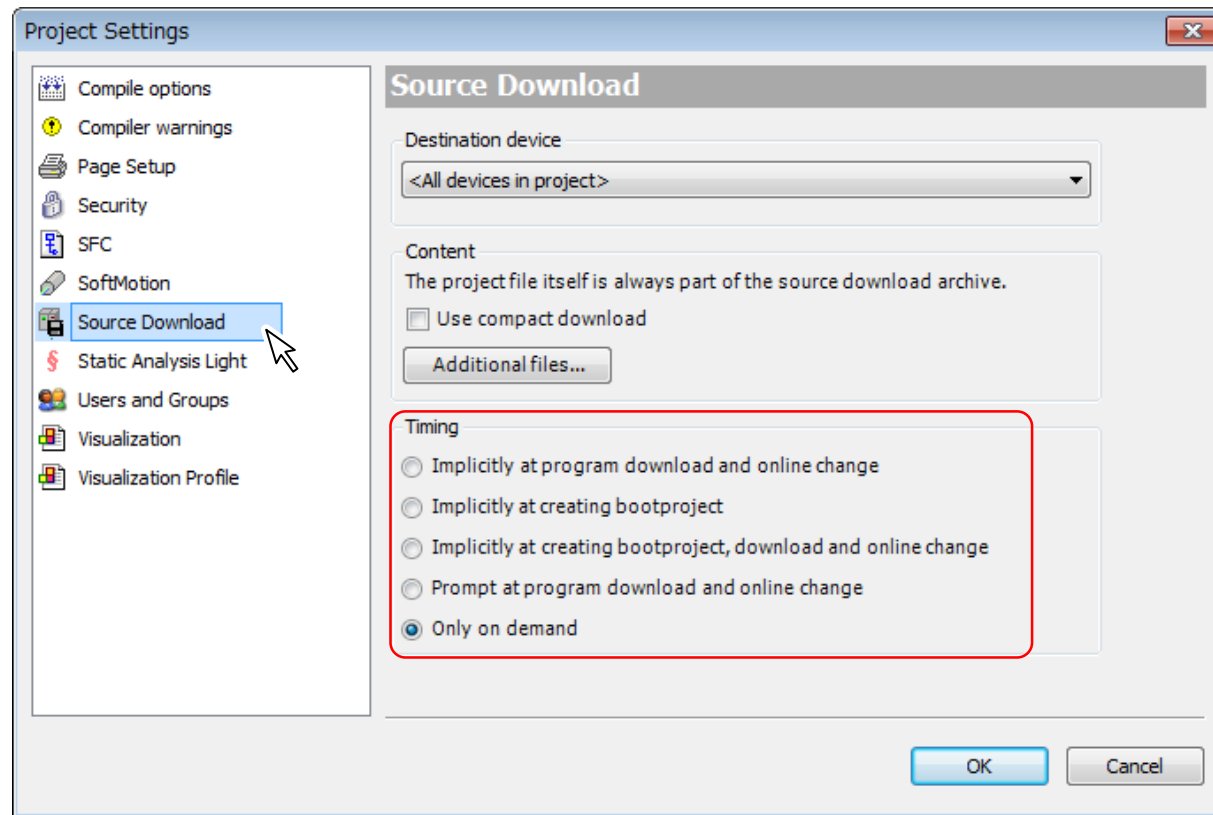


If the source program is not saved as a file, the following dialog window will be displayed. Click [Yes] to save the project and continue with the source download.



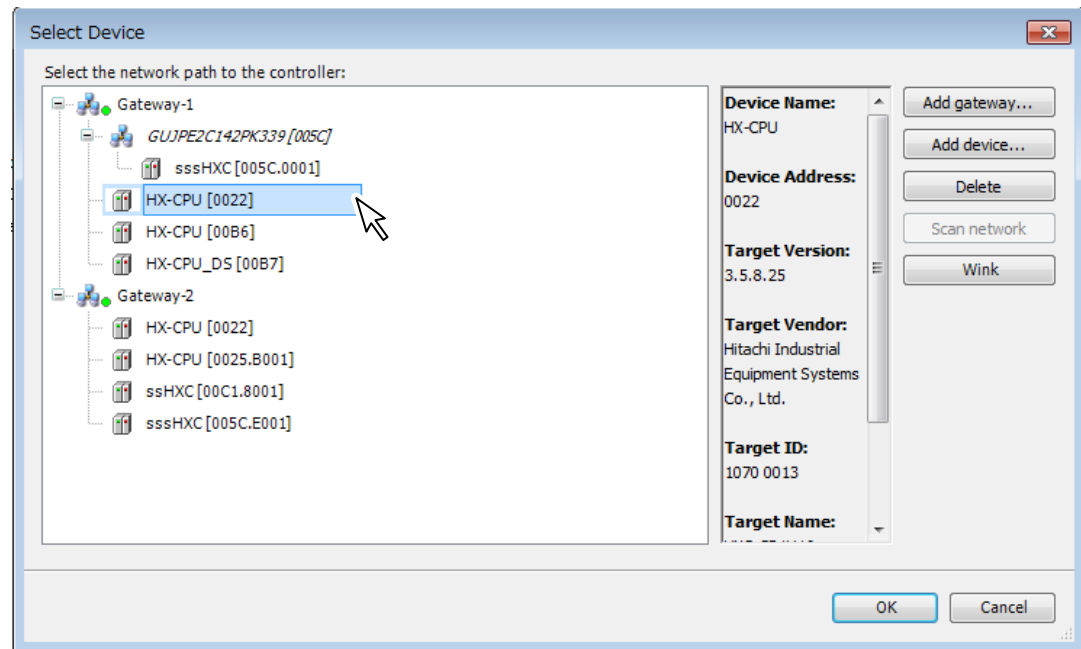
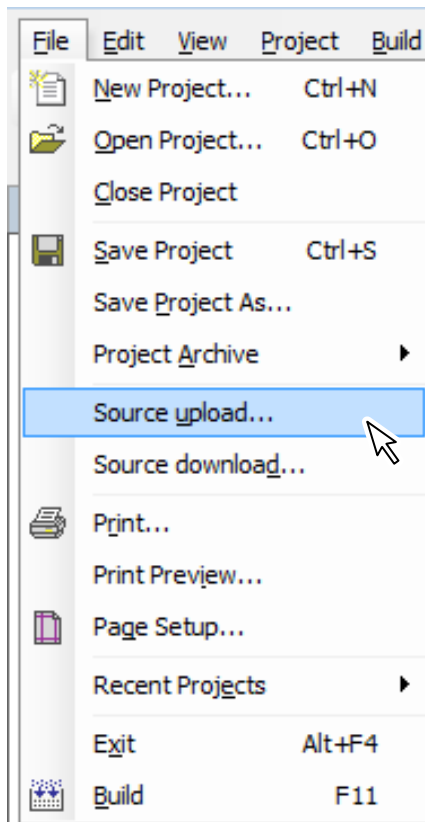
## Source download (Another way)

Downloaded timing of source file can be set in the menu [Project]-[Project Settings]-[Source Download]. The default setting is [Only on demand].



## Source upload

- ① Click [File]-[Source upload]
- ② Select a device to upload the source program in [Select Device] window.



## I/O refresh

Only I/Os used in POU are updated. So if login with empty program and digital input is activated, the status is not seen correctly in the mapping table.

Variable	Mapping	Channel	Address	Type	Default Value	Unit	Description
Switch_10		Bit0	%IW0	WORD			
Temp_over		Bit1	%IX1.0	BOOL	FALSE		
Temp_under		Bit2	%IX1.1	BOOL	FALSE		
Door_open		Bit3	%IX1.2	BOOL	FALSE		
Door_close		Bit4	%IX1.3	BOOL	FALSE		
Switch_20		Bit5	%IX1.4	BOOL	FALSE		
Application.PLC_P...		Bit6	%IX1.5	BOOL	FALSE		
		Bit7	%IX1.6	BOOL	FALSE		
		Bit8	%IX1.7	BOOL	FALSE		
		Bit9	%IX0.0	BOOL	FALSE		
		Bit10	%IX0.1	BOOL	FALSE		
		Bit11	%IX0.2	BOOL	FALSE		
		Bit12	%IX0.3	BOOL	FALSE		
		Bit13	%IX0.4	BOOL	FALSE		
		Bit14	%IX0.5	BOOL	FALSE		
		Bit15	%IX0.6	BOOL	FALSE		
			%IX0.7	BOOL	FALSE		

Reset mapping  Always update variables

Default Value	Current Value
FALSE	TRUE
FALSE	TRUE
FALSE	FALSE
FALSE	FALSE
FALSE	TRUE
FALSE	FALSE
FALSE	TRUE
FALSE	FALSE
FALSE	FALSE

Enable "Always update variables" to update all I/Os.

Possible to set in "PLC settings"

## Run/Stop status and Run/Stop switch

Run/Stop from CoDeSys works only when RUN/STOP switch position is in **RUN**.

Operation Switch position	Stop by CoDeSys	Run by CoDeSys	Power ON
STOP	Stop	Stop	Stop
RUN	Run → Stop	Stop → Run	Run

In case of EH/EHV, remote operation works only when switch position is in **STOP**.

Operation Switch position	Stop by PC	Run by PC	Power ON
STOP	Run → Stop	Stop → Run	Stop
RUN	Run	Run	Run

## Stop and Reset

CPU has 3 different operations, **Stop**, **Reset warm** and **Reset cold** to stop PLC.

**Stop** or **Reset warm** can be assigned to stop position of RUN/STOP switch. The default setting is **Reset warm**.

When CPU stops with error (exception), **Reset warm** or **Reset cold** must be operated to reset error status.

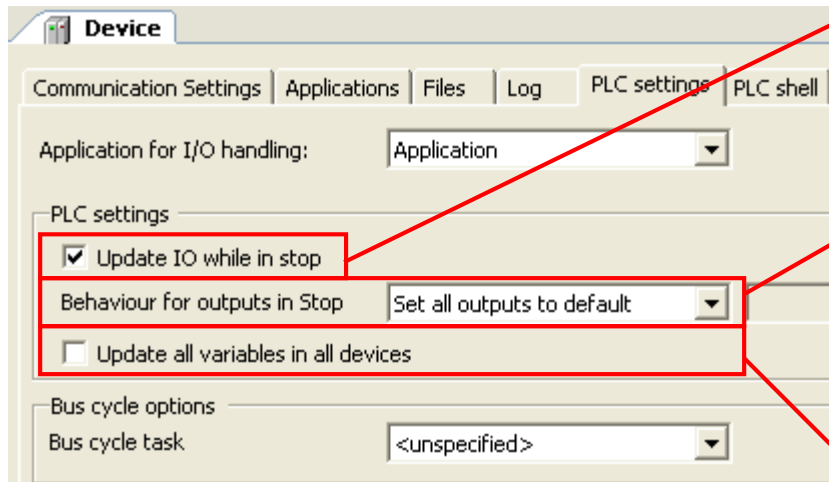
Operations \ CPU status	Run/Stop	Error	variables	Retain variables
Stop	Run → Stop	Remains	Remains	Remains
Reset warm	Run → Stop	<b>Reset error</b>	<b>Return to default</b>	Remains
Reset cold	Run → Stop	<b>Reset error</b>	<b>Return to default</b>	<b>Return to default</b>

## Status of variables and program for users' operations

target \ Operations	VAR	VAR RETAIN	VAR PERSISTENT	Application (RAM)	Boot application (FLASH)
STOP	-	-	-	-	-
Reset warm	X	-	-	-	-
Reset cold	X	X	-	-	-
Reset origin	X	X	X	X	X
Download	X	X	-	updated	Depends on setting
Online Change	-	-	-	update	Depends on setting
Reboot PLC (Power OFF/ON)	X	-	-	X	-

-: remain X: initialized

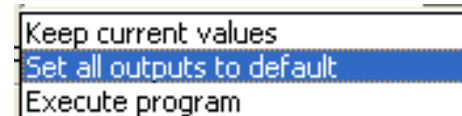
## PLC settings



Update IO while in stop  
(default: enable)

Behavior for output in stop (Note1)

- Keep current values
- Set all outputs to default (Note2)
- Execute program



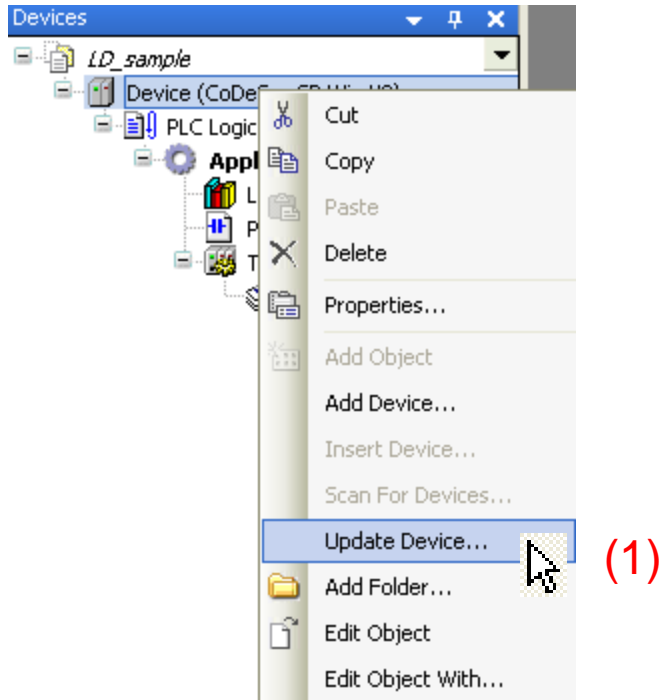
Update all variables in all devices  
(independent from used or not.)  
Default : disable

**Note1:** This parameter is valid only when “Reset all outputs in STOP” is set as No.  
If this is Yes, all I/Os are initialized as 0 by hardware.

**Note2:** Default values are configured in I/O Mapping table.

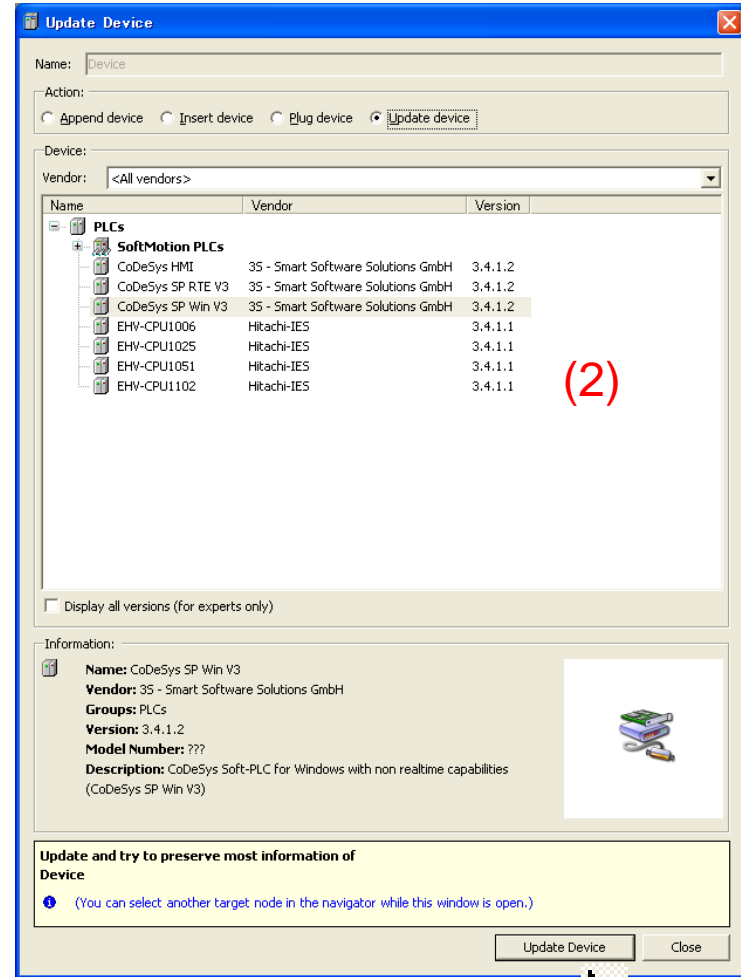
## Change CPU type

(1) Right mouse click at Device in the project tree and choose Update Device.



(2) Choose CPU in the dialog.

(3) Click [Update Device]



**END**